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Rural land development under hyperbolic discounting: a real option approach*

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Abstract

This article presents a simple model of land development under uncertainty and hyperbolic discounting. Land kept in rural use pays an uncertain rent, while net returns from land development are known and constant. The landowner is viewed here as a sequence of infinite autonomous selves with time-inconsistent preferences. We solve the underlying noncooperative intra-personal stopping time game under both naïve and sophisticated beliefs about the landowner's time-inconsistency and show that i) land development is accelerated due to his present-biased time preferences and ii) a higher acceleration is associated with sophistication.

Keywords: Land Development, Stochastic Hyperbolic Discounting, Timing Game, Real Options.

Jel classification: C61, Q15, R11.

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1. Introduction

Use of exponential discounting dominates the literature investigating land development decisions as: i) it lowers the burden in terms of mathematical complexity and, very importantly, ii) it guarantees the time consistency of any development plan set by the landowner due to the underlying assumption of a constant rate of time preference.

However, a constant rate of time preference is a strong assumption that has been hotly debated since Strotz (1956) proposed, as a more "reasonable" alternative,¹ time-declining discount rates. Strotz's conjecture has since found empirical support, as several experiments have provided evidence of individuals' taste for immediate gratification (see Loewenstein and Prelec, 1992, for a review). This has led to a series of papers using hyperbolic rather than exponential functions in model setup (see Frederick et al., 2002, for a review). Concerning landowners, empirical support for quasihyperbolic discounting has been found by Salois and Moss (2011) in a study based on US farmland values. However, efforts to introduce hyperbolic discounting in the theoretical frame investigating land development decisions have been quite limited and, to our knowledge, are represented solely by the model provided in Salois (2012). Salois introduces a quasi-hyperbolic landowner in the standard model of land development proposed by Irwin and Bockstael (2002) and shows that, by increasing the rate of land conversion, quasi-hyperbolic discounting may induce overdevelopment of rural land.

The analysis in Salois (2012) is performed in a deterministic frame and thus does not permit consideration of the relevant impact that uncertainty about payoffs associated with land uses may have on the decision to develop and on its timing. In fact, as widely recognised in the literature (see for instance Capozza and Helsley, 1990; Capozza and Li, 1994; Geltner et al., 1996), the option value associated with the decision to be taken may make postponing development the optimal choice in order to gather information about its future benefits.

The present study aims to fill this gap by investigating the land development problem under hyperbolic discounting in a real option frame. This enables examination of how two conflicting elements, namely hyperbolic discounting on the one hand, inducing a rush in land development and option value on the other hand inducing delay, affect the decision and timing of land development.

¹Referring to exponential discounting, Strotz (1956) argues that there is "no reason why an individual should have such a special discount function" (p.172).

Since, as noted by Strotz, declining discount rates may lead to time inconsistent planning, the impact of agents' self-awareness about their time inconsistency on the decision and timing of land development is also explicitly investigated. This is done by considering i) a landowner who fully ignores his time inconsistency (*naïve*) and ii) a landowner who perfectly foresees that his time preferences change over time (*sophisticated*) (see O'Donoghue and Rabin, 1999).

Previous papers studying real options in the framework of time inconsistent preferences are those by Grenadier and Wang (2007) and Di Corato (2012). Grenadier and Wang (2007) investigate the impact of hyperbolic discounting on investment plans and show that the timing of investment differs from that set by an exponential discounter and depends on: i) agents' self-awareness about their time inconsistency and ii) the payoff form, i.e. a lump sum rather than a sequence of cash flows. Di Corato (2012) considers a forest-cutting problem in a dynamic game played by three nonoverlapping, imperfectly altruistic generations, each of which is viewed as a hyperbolic discounting agent, and shows that, compared with the harvesting policy set by an exponential agent, the option value attached to the decision to harvest is lower and earlier harvest occurs. That result holds under both *naïve* and *sophisticated* beliefs but under *sophistication* harvest occurs earlier than under *naïveté*.

The present study considers a standard land development problem where land kept in rural use pays a rent following geometric Brownian motion and net returns from land development are known and constant.² In line with the literature, the hyperbolic landowner is viewed as a sequence of infinite autonomous *selves* with time-inconsistent preferences (see Grenadier and Wang, 2007; Harris and Laibson, 2013). Each *self* is allowed to exercise the option to develop only during his life and cares about, but has no control over, the decisions taken by his future *selves*. The life of these *selves* is random and regulated by a Poisson death process. Each *self* determines his optimal threshold for exercise of the option to develop by solving the underlying non-cooperative intra-personal stopping game on the basis of his beliefs about the behaviour of future *selves*.

It is found that a hyperbolic landowner always develops land earlier than an exponential

²Grenadier and Wang (2007) study the optimal exercise of an American call option on investment under hyperbolic discounting. The present study, in contrast, is dealing with the optimal exercise of an American put-like option to "disinvest", by selling land to a developer. Note also that in our frame holding the option pays a periodic rent (associated with rural use) as a sort of dividend.

landowner. The reasoning is straightforward. Under hyperbolic discounting, the bias for present gratification lowers the value associated with holding the option to develop. Hence, each *self* finds convenient anticipating future *selves* by killing the option earlier. Interestingly, this study shows that a *sophisticated* landowner rushes land development more than a *naïve* landowner. In fact, due to his perfect foresight, a *sophisticated* landowner, takes into account the cost of changes in the development timing strategy that are sub-optimal from his time perspective. Hence, compared with a *naïve* landowner totally ignoring this cost, the sophisticated landowner has a further argument for anticipating future *selves* by killing the option to develop.

The remainder of this paper is organised as follows. Section 2 presents the basic set-up. In Section 3, the value of land and the timing of land development under hyperbolic discounting are determined, under the assumption of both *naïve* and *sophisticated* beliefs. The results are then compared and discussed using the case of an exponential landowner as the benchmark. Section 4 concludes. The Appendix contains the proofs omitted from the text.

2. The basic set-up

Consider a risk-neutral, infinite-lived landowner owning a parcel of land currently kept in rural use (agriculture, forestry, open space etc.). Under the current destination, the landowner earns a rent $\{R(t) : t \ge 0\}$. Assume that R(t) is stochastic and evolves according to the following diffusion:

$$dR(t)/R(t) = \alpha dt + \sigma dQ(t), \text{ with } R(0) = R$$
(1)

where α and σ are the drift and volatility rates, respectively, and $\{Q(t)\}\$ is a standard Wiener process with E[dQ] = 0 and $E[(dQ)^2] = dt$.

At any t > 0, the landowner can sell his land to a developer, converting it into an urban use. Here it is assumed that land development is irreversible³ and the net pay-off⁴ accruing to the landowner selling his land is denoted P > 0.5

³Note that, taking a real options perspective, the landowner can be viewed as holding an American put option, i.e. the option to develop, paying P if exercised. Otherwise, i.e. the land kept in rural use, the landowner receives R(t) as a sort of dividend.

⁴As in Salois (2011), the pay-off P results from the sales price net of any conversion costs (administrative fees, permit expenses, institutional costs or necessary infrastructure expenditures, etc.).

⁵Note that one can easily allow for a stochastic P following geometric Brownian motion. The model would in fact be the same once R(t) is normalised in terms of P (see Geltner et al., 1996, p. 26).

2.1 The discount function

The time preferences of a hyperbolic landowner are characterised here by adopting the discount function proposed by Harris and Laibson (2013), where the hyperbolic discounting agent is viewed as an infinite sequence of risk-neutral *selves*, i = 0, 1, 2, Each *self i* divides time into *present* and *future*. The *present* lasts a random time period, $s_{i+1} - s_i$, where s_i and s_{i+1} are the birth dates of *self i* and *self i* + 1. The transition is regulated by a Poisson death process with intensity $\lambda \in (0, \infty)$. The *future*, from the perspective of *self i*, starts at s_{i+1} and lasts forever. Each *self i* discounts 1) exponentially, at a constant rate ρ , both *present* and *future* payoffs and 2) additionally, by the factor $\beta \in (0, 1)$ all *future* payoffs. Summing up, his discount function is defined as follows:

Definition 1 At time t for any $\beta \in (0,1)$ and $\lambda \in (0,\infty)$, the self i's discount function is given by the following function:

$$D_{i}(s,t) = \begin{cases} e^{-\rho(t-s)}, & if \quad t \in [s_{i}, s_{i+1}), \\ \beta e^{-\rho(t-s)}, & if \quad t \in [s_{i+1}, \infty), \end{cases}$$

for $t > s$ and $s_{i} \leq s \leq s_{i+1}.$ (2)

From Eq. (2), as $\beta \in (0, 1)$, a dollar paid to the generic *self i* in the *future* would be worth less than a dollar paid in the *present*. Note that in the limit cases $\beta \to 1$ and $\beta \to 0$, the agent would discount exponentially at rate ρ and $\rho + \lambda$, respectively, where λ is the "*speed*" at which time preferences change over time.⁶ Note also that:

i) The expected value of $D_i(s, t)$, i.e.

$$E[D_i(s,t)] = e^{-(\rho+\lambda)(t-s)} + \beta(1-e^{-\lambda(t-s)})e^{-\rho(t-s)} = \beta e^{-\rho(t-s)} + (1-\beta)e^{-(\rho+\lambda)(t-s)}, \quad (2.1)$$

is a convex combination of two exponential discount functions using ρ and $\rho + \lambda$ as discount rates.

ii) The derivative of $E[D_i(s,t)]$ with respect to time is:

$$\partial E[D_i(s,t)]/\partial t = -[\rho\beta e^{-\rho(t-s)} + (\rho+\lambda)(1-\beta)e^{-(\rho+\lambda)(t-s)}\}] < 0.$$
(2.2)

⁶The probability of having a new self born in the next time interval dt is equal to λdt . Hence, consistently, when $\beta \to 0$ the discount rate is adjusted in order to account for the "sudden death" of the current self.

This implies that the discount factor increases as t comes nearer or that, in other words, payoffs are discounted at the following time-declining rate:

$$-(\partial E[D_i(s,t)]/\partial t)/E[D_i(s,t)] = \rho + \lambda(1-\beta)e^{-(\rho+\lambda)(t-s)}/E[D_i(s,t)].$$

$$(2.3)$$

3. Value of land and timing of land development

In order to provide a benchmark, in this section the standard land development problem faced by a landowner who discounts future payoffs exponentially is first solved. A hyperbolic landowner with the time preferences presented above is then considered. This landowner discounts future payoffs at time-declining rates and may formulate time-inconsistent plans, i.e. he may formulate plans which may later be disobeyed and revised. The analysis then proceeds by allowing for two extreme assumptions concerning the landowner's self-awareness about his time-inconsistency. First a *naïve* agent, i.e. an agent who ignores his time inconsistency and believes that his future *selves* will act according to his current time preferences, is considered. A *sophisticated* agent, i.e. an agent who perfectly foresees that his time preferences change over time, is then considered. Under *naïveté*, the timing strategy set by the current *self* will be formulated viewing future *selves* as "*committed*" to his plan of action. Under *sophistication*, in contrast, the current *self* sets the strategy, being aware that future *selves* are going to "*disobey*".⁷ The resulting timing strategy then takes into account the sub-optimality, from the present *self*'s time perspective, associated with the timing strategies set by his future *selves*.

3.1 An exponential landowner

The landowner discounts exponentially future payoffs⁸ at the constant discount rate $\rho > \alpha$.⁹ Assume that it is currently worth keeping land in rural use, i.e. $R > R^*$ where R^* is the revenue threshold triggering land development.

⁷The present study focuses on "*consistent planning*", i.e. the agent do not choose plans that are going to be disobeyed. It does not consider the alternative possibility of selecting a "*strategy of precommitment*" which would require committing to a certain plan of action (see e.g. Pollak, 1968; Strotz, 1956).

⁸ The analysis in this section is consistent with the limit case where $\beta \to 1$ in Eq. (2).

⁹This restriction is needed in order to ensure convergence. Note that if $\rho \leq \alpha$ land development would be never optimal.

Using standard arguments, in the continuation region $R > R^*$, the value of land, V(R), is the solution of the following problem:

$$V(R) = \max_{R} \left\{ P, Rdt + e^{-\rho dt} E\left[V(R+dR)\right] \right\},\tag{3}$$

By Ito's lemma, Eq. (3) can be rearranged as:

$$(1/2)\sigma^2 R^2 V''(R) + \alpha R V'(R) - \rho = -R, \text{ for } R > R^*.$$
 (3.1)

Solving Eq. (3.1) yields the following proposition:

Proposition 1 Under exponential discounting,

i) land development occurs when revenues from rural land use reach the threshold

$$R^* = [\gamma/(\gamma - 1)]P(\rho - \alpha); \tag{4}$$

ii) the value of land is equal to:

$$V(R; R^*) = [P - R^* / (\rho - \alpha)](R/R^*)^{\gamma} + R / (\rho - \alpha),$$
(5)

where γ is the negative root of the characteristic equation $\Lambda(\gamma) = (1/2)\sigma^2\gamma(\gamma-1) + \alpha\gamma - \rho = 0.$

Proof. See section A.1 in Appendix.

Examining the threshold in Eq. (4), it can be seen that:¹⁰ i) the higher the expected growth rate, α , for returns from rural uses, the lower the critical threshold and the later, in expected terms, land is converted in urban use, i.e. $\partial R^*/\partial \alpha < 0$; ii) as returns from rural uses become more volatile, the critical threshold is lowered and land development is postponed, i.e. $\partial R^*/\partial \sigma^2 > 0$; iii) the higher the discount rate, the earlier land is converted, i.e. $\partial R^*/\partial \rho > 0$; and iv) the higher the future net returns from urban use, the earlier land is converted, i.e. $\partial R^*/\partial \rho > 0$.

In Eq. (5), the first term represents the value of the option to develop land, i.e. the net returns from development, P, minus the present value of forgone returns from rural land use, $R^*/(\rho - \alpha)$. Note that this payoff materialises only if R reaches R^* . Hence, consistently, the payoff is discounted using the stochastic discount factor $(R/R^*)^{\beta}$ which accounts for the probability of hitting R^* . The

¹⁰These results are pretty standard in the literature, see for instance Capozza and Helsley (1990) and Capozza and Li (1994).

second term in Eq. (5) is the expected present value of returns from rural land use. This would be the value accruing to the landowner if the condition triggering land development were not achieved. In this respect, note that as $R^* \to 0$, the value of the option to develop vanishes as, by Eq. (1), R(t) > 0 and $\lim_{R^*\to 0} V(R; R^*) = R/(\rho - \alpha)$.

3.2 A hyperbolic naïve landowner

The present self *i* discounts by $e^{-\rho dt}$ any payoff accruing in the time interval (s, s_{i+1}) and by $\beta e^{-\rho dt}$ the pay-offs accruing in the interval $[s_{i+1}, \infty)$. Under *naïveté*, self *i* believes that the entire sequence of successive selves, i.e. selves in the interval $[s_{i+1}, \infty)$, will take decisions concerning the destination of land according to his own time preferences, i.e. $D_i(s,t)$. This implies that self *i* views these selves as standard exponential discounters using ρ as discount rate and having the following plan of action:

keep land in rural use, if
$$R > R^*$$
,
sell land, if $R \le R^*$. (S.1)

Self *i* solves the land development problem on the basis of his beliefs and sets \mathbb{R}^n as the critical threshold. If $\mathbb{R}(t)$ hits \mathbb{R}^n before the next self is born, self *i* cashes the flow of rents accruing up to the land sale plus the sale net pay-off *P*. Otherwise, if self *i* + 1 is born before $\mathbb{R}(t)$ hits \mathbb{R}^n , self *i* benefits from the flow of rents accruing in the period (s, s_{i+1}) plus the expected present value of the pay-offs cashed by future selves. Consistently with his beliefs, i.e. future selves developing at \mathbb{R}^* , this continuation value is equal to:

$$V_c^n(R;R^*) = \beta \cdot V(R;R^*)$$

Assume that it is currently worth keeping land in rural use, i.e. $R > R^n$. The present *self i* must then solve the following problem:

$$V^{n}(R) = \max_{R} \{P, Rdt + e^{-\lambda dt} E\left[e^{-\rho dt}V^{n}(R+dR)\right] + \left(1 - e^{-\lambda dt}\right) E\left[e^{-\rho dt}V^{n}_{c}(R+dR;R^{*})\right]\}.$$
 (6)

By Ito's lemma, Eq. (6) can be rearranged as:

$$(1/2)\sigma^2 R^2 V^n''(R) + \alpha R V^n'(R) - \rho V^n(R) = -\{R + \lambda [V_c^n(R; R^*) - V^n(R)]\}.$$
 (6.1)

Solving Eq. (6.1) yields the following proposition:

Proposition 2 Under hyperbolic discounting and naïve beliefs,

i) the land development threshold \mathbb{R}^n is the solution of the following equation:

$$\beta[(\theta - \gamma)/(\theta - 1)][P - R^*/(\rho - \alpha)](R^n/R^*)^{\gamma} + \eta[R^n/(\rho - \alpha)] - [\theta/(\theta - 1)]P = 0;$$
(7)

ii) land is, in expected terms, developed earlier than under exponential discounting, i.e. $R^n > R^*$;

iii) the value of land is equal to:

$$V^{n}(R; R^{n}, R^{*}) = \{P - \beta [P - R^{*}/(\rho - \alpha)](R^{n}/R^{*})^{\gamma} - \eta [R^{n}/(\rho - \alpha)]\}(R/R^{n})^{\theta} + \beta [P - R^{*}/(\rho - \alpha)](R/R^{*})^{\gamma} + \eta [R/(\rho - \alpha)], \text{ for } R > R^{n},$$
(8)

where $\eta = (\rho + \lambda\beta - \alpha)/(\rho + \lambda - \alpha) \le 1$ and θ is the negative root of the characteristic equation $\Omega(\theta) = (1/2)\sigma^2\theta(\theta - 1) + \alpha\theta - (\rho + \lambda) = 0.$

Proof. See section A.2 in Appendix.

The critical threshold \mathbb{R}^n set by a hyperbolic *naïve* landowner is higher than that set by an exponential landowner. This implies that, in expected terms, land is developed earlier. This makes sense considering that, due to his present-biased time preferences, the value of keeping open the option to develop has lower value for *self i*. Note in fact that the value associated with this option when held by his future *selves*, i.e. the flow of rents accruing up to the land sale plus the sale net pay-off P, is lowered by the terms $\eta < 1$ and $0 < \beta < 1$, respectively. Hence, the optimal timing strategy for *self i* is anticipating his future *selves* by setting a higher threshold for exercise of the option to develop. Note that $d\mathbb{R}^n/d\beta < 0$ and $d\mathbb{R}^n/d\lambda > 0$. This means that the higher the present bias, i.e. the lower β and/or the higher λ , the earlier land development occurs.

Finally, note that the timing strategy set by a hyperbolic *naïve* landowner is based on the belief that his future *selves* are committed to S.1, i.e. the timing strategy set by the current *self*. This belief is, of course, unfounded. In fact, as soon as the next *self* i + 1 is born, he will not adopt the threshold R^* as believed by *self* i, but will set his timing strategy on the basis of his own time preferences, i.e. using $D_{i+1}(s,t)$. Given that, by assumption, the sequence of *selves* is infinite and *naïveté* persistent, each newly born *self* faces the same decision problem solved above for *self* i. Hence, it can be concluded that the actual critical threshold for exercise of the option to develop land is unique and equal to $R^n > R^*$.

3.3 A hyperbolic sophisticated landowner

A sophisticated self *i* has perfect foresight and anticipates that his future selves may later revise his plan of action. Hence, his plan should be set taking into account that, from his time perspective, future selves' timing strategies may be sub-optimal. In the present frame, the landowner is viewed as a sequence of infinite selves each having their own time preferences, i.e. $D_i(s,t)$. However, as each self is followed by an infinite number of selves, the land development problem that each generic self must solve is the same. Hence, as they would all consider optimal developing land when the same critical time threshold is reached, their timing strategy can be determined by imposing stationarity to the solution of the underlying non-cooperative intra-personal timing game.

Consider the generic self *i* and denote i) by \tilde{R} his conjecture about the critical development threshold set by his future selves and ii) by $g(\tilde{R})$ his own critical development threshold. Note that, as his timing strategy must be consistent with his beliefs, the threshold $g(\tilde{R})$ is a function of the conjectured threshold \tilde{R} .

Future selves have the following plan of action:

keep land in rural use, if
$$R > \tilde{R}$$
,
sell land, if $R \le \tilde{R}$. (S.2)

Hence, as above, given S.2 and his time perspective, self i's continuation value is equal to:

$$V_c^s(R;\widetilde{R}) = \beta \{ [P - \widetilde{R}/(\rho - \alpha)] (R/\widetilde{R})^{\gamma} + R/(\rho - \alpha) \}$$

Assume that $R > g(\tilde{R})$. The present *self* i must then solve the following problem:

$$V^{s}(R) = \max_{R} \{P, Rdt + e^{-\lambda dt} E\left[e^{-\rho dt} V^{s}(R+dR)\right] + \left(1 - e^{-\lambda dt}\right) E\left[e^{-\rho dt} V^{s}_{c}(R+dR;\widetilde{R})\right]\}, \quad (9)$$

By Ito's lemma, Eq. (9) can be rearranged as:

$$(1/2)\sigma^2 R^2 V^{s''}(R) + \alpha R V^{s'}(R) - \rho V^s(R) = -\{R + \lambda [V_c^s(R; \widetilde{R}) - V^s(R)]\}.$$
(9.1)

Solving Eq. (9.1) gives:

$$V^{s}(R;h(\widetilde{R}),\widetilde{R}) = \{P - \beta[P - \widetilde{R}/(\rho - \alpha)](g(\widetilde{R})/\widetilde{R})^{\gamma} - \eta[g(\widetilde{R})/(\rho - \alpha)]\}(R/g(\widetilde{R}))^{\theta} + \beta[P - \widetilde{R}/(\rho - \alpha)](R/\widetilde{R})^{\gamma} + \eta[R/(\rho - \alpha)], \text{ for } R > g(\widetilde{R}),$$

$$(9.2)$$

where $g(\tilde{R})$ is the solution of the following equation:

$$\beta[(\theta - \gamma)/(\theta - 1)][P - \widetilde{R}/(\rho - \alpha)](g(\widetilde{R})/\widetilde{R})^{\gamma} + \eta[g(\widetilde{R})/(\rho - \alpha)] - [\theta/(\theta - 1)]P = 0.$$
(9.3)

By imposing the stationarity condition $g(\tilde{R}) = \tilde{R} = R^s$, it can be shown that:

Proposition 3 Under hyperbolic discounting and sophisticated beliefs,

i) the land development threshold is

$$R^{s} = \frac{\theta + \beta(\gamma - \theta)}{\eta(\theta - 1) + \beta(\gamma - \theta)} P(\rho - \alpha);$$
(10)

ii) land is, in expected terms, developed earlier than under naïve beliefs, i.e. $R^s > R^n$, and

$$R^* < R^s < R^{**} = [\theta/(\theta - 1)]P(\rho + \lambda - \alpha);$$
(10.1)

iii) the value of land is equal to:

$$V(R; R^{s}) = (1 - \beta) \{ [P - R^{s} / (\rho + \lambda - \alpha)] (R/R^{s})^{\theta} + [R/(\rho + \lambda - \alpha)] \} + \beta \{ [P - R^{s} / (\rho - \alpha)] (R/R^{s})^{\gamma} + [R/(\rho - \alpha)] \}, \text{ for } R > R^{s}$$
(11)

Proof. See sections A.2 and A.3 in Appendix.

The critical threshold, R^s , is increasing in the degree of present bias, i.e. $dR^s/d\beta < 0$ and $dR^s/d\lambda > 0$. In the limit cases $\beta \to 1$ and $\beta \to 0$, the threshold converges toward R^* and R^{**} , i.e. the critical thresholds that would be set by an exponential discounter using ρ and $\rho + \lambda$ as discount rates, respectively. The threshold R^s is higher than R^* . As for the case of a *naïve* landowner, this is again due to the need for avoiding, by killing the option, the passage of *self i*'s holdings, i.e. the flow of rents plus the option to develop, to future *selves*. In this respect, note that under *sophistication* the incentive for anticipating future *selves* is even higher and leads to the definition of a threshold R^s higher than that set by a *naïve* landowner. This makes the actual exercise by *self i* of the option to develop even more likely than under *naïveté*. The reasoning behind this result is straightforward. *Self i* in fact, being aware of his time inconsistency, fully internalises the cost of sub-optimal (from his time perspective) timing strategies set by his future *selves*. This cost makes the value associated with holding the option to develop even lower than for the case of a *naïve* landowner. Last, the threshold R^s is lower than R^{**} , i.e. the threshold corresponding to the case

where the arrival of the next *self* would, as $\beta \to 0$, substantially absorb any value associated with *self* i's holdings.

Finally, the value function in Eq. (11) results from the weighted sum of the two value functions that an exponential discounter would have using $\rho + \lambda$ and ρ as discount rates, respectively, and fixing R^s as the threshold for exercise of the option to develop. This is of course consistent, as clearly illustrated by Eq. (2.1), with the expected discount rate associated with the time preferences of the *sophisticated* hyperbolic agent considered.

4. Conclusions

This paper examines the implications of hyperbolic time preferences for the timing of development of rural land. It extends the previous model by Salois (2012) in order to account for i) uncertainty about payoffs associated with the asset land and ii) self-awareness about the planning time inconsistency implied by the assumed time preferences. The results show that the impact of option value considerations leading, as uncertainty increases, to the postponement of land development is lower under hyperbolic time preferences. In fact, due to the present bias induced by the implicit time-declining discount rate, the value associated with holding open the option to develop is lower and, as a consequence, the hyperbolic landowner prefers earlier land development than in the case of an exponential landowner. It is found that a *sophisticated* hyperbolic landowner sets a higher threshold for exercise of the option to develop compared with a *naïve* landowner. In fact, a *sophisticated* landowner, being aware that the plan initially set may be later revised, sets his timing strategy by fully internalising the cost associated with the sub-optimality of future changes in the strategy. In contrast, this cost is totally missed by a *naïve* landowner, who believes that the development timing strategy initially set would be not violated. Hence, a further argument rushing land development emerges under *sophistication*.

These findings refer to land development problems, but may also prove useful for other issues characterising land-use change, such as farmland abandonment, land conservation and competition for land for cultivation of food or energy crops.¹¹

¹¹See Nishihara (2002), Schatzki (2003) and Song et al. (2011), respectively.

Appendix

A.1 Exponential discounting

As standard, to guarantee optimality,¹² the solution of the differential Eq. (3.1) must meet the following *value-matching* and *smooth-pasting* conditions:

$$V(R^*) = P, V'(R^*) = 0.$$
 (A.1.1-A.1.2)

A candidate solution for Eq. (3.1) takes the form:¹³

$$V(R) = kR^{\gamma} + R/(\rho - \alpha), \qquad (A.1.3)$$

where k is a constant to be determined and γ is the negative root of the characteristic equation $\Lambda(\gamma) = (1/2)\sigma^2\gamma(\gamma - 1) + \alpha\gamma - \rho = 0.$

Substituting Eq. (A.1.3) into Eq. (A.1.1) and Eq. (A.1.2) yields:

$$\begin{cases} kR^{*\gamma} + R^*/(\rho - \alpha) = P, \\ k\gamma R^{*\gamma - 1} + 1/(\rho - \alpha) = 0. \end{cases}$$

Solving this system gives k and R^* . Plugging k into Eq. (A.1.3) yields Eq. (5).

A.2 Hyperbolic discounting

Eq. (6.1) and Eq. (9.1) are technically similar. Proceed by solving first the underlying common problem and then characterising the solution according to the assumed beliefs concerning future *selves*' time preferences.

The equation to be solved is:

$$(1/2)\sigma^{2}R^{2}V^{q}''(R) + \alpha RV^{q}'(R) - (\rho + \lambda)V^{q}(R)$$

$$= -\{R[1 + \lambda\beta/(\rho - \alpha)] + \lambda\beta\{[P - \overline{R}^{q}/(\rho - \alpha)](R/\overline{R}^{q})^{\gamma}\}$$
(A.2.1)

¹²See Dixit and Pindyck (1994, Ch. 4).

¹³The solution for the homogeneous part of Eq. (3.1) should have the form $V_h(R) = k_1 R^{\gamma_1} + k_2 R^{\gamma_2}$ where k_1 and k_2 are constants to be determined while $\gamma_1 > 0$ and $\gamma_2 < 0$ are the roots of the characteristic equation $\Lambda(\gamma) = 0$. However, as $R \to \infty$, the value of the option to develop goes to zero. Thus, as $\gamma_1 > 0$, then k_1 must be zero, otherwise $\lim_{R\to\infty} V_h(R) = \infty$.

where

$$q = n \text{ and } \overline{R}^n = R^*, \text{ if the agent is } na\"ive,$$

 $q = s \text{ and } \overline{R}^s = \widetilde{R}, \text{ if the agent is sophisticated.}$

Suppose that the particular solution for Eq. (A.2.1) takes the form $V^q(R) = c_1 R^{\gamma} + c_2 R$. Substituting this candidate form and its first two derivatives, $\partial V^q(R) / \partial R = c_1 \gamma R^{\gamma-1} + c_2$ and $\partial^2 V^q(R) / \partial R^2 = c_1 \gamma (\gamma - 1) R^{\gamma-2}$ into Eq. (A.2.1) yields:

$$\{[(1/2)\sigma^{2}\gamma(\gamma-1) + \alpha\gamma - \rho] - \lambda\}c_{1}R^{\gamma} + [\alpha - (\rho + \lambda)]c_{2}R$$

$$= -\{R[1 + \lambda\beta/(\rho - \alpha)] + \lambda\beta\{[P - \overline{R}^{q}/(\rho - \alpha)](R/\overline{R}^{q})^{\gamma}\}$$
(A.2.2)

The coefficients c_1 and c_2 can be determined by solving the following two equations:

$$\{[(1/2)\sigma^2\gamma(\gamma-1) + \alpha\gamma - \rho] - \lambda\}c_1 = -\lambda\beta[P - \overline{R}^q/(\rho - \alpha)](1/\overline{R}^q)^{\gamma}$$
$$[\alpha - (\rho + \lambda)]c_2 = -[1 + \lambda\beta/(\rho - \alpha)]$$

Solving both equations yields:

$$c_{1} = \beta [P - \overline{R}^{q} / (\rho - \alpha)] (1/\overline{R}^{q})^{\gamma}$$

$$c_{2} = [1 + \lambda \beta / (\rho - \alpha)] / (\rho + \lambda - \alpha) = \eta / (\rho - \alpha)$$

where $\eta = (\rho + \lambda\beta - \alpha)/(\rho + \lambda - \alpha) \le 1$.

The general solution then takes the form:¹⁴

$$V^{q}(R;\overline{R}^{q}) = kR^{\theta} + \beta[P - \overline{R}^{q}/(\rho - \alpha)](R/\overline{R}^{q})^{\gamma} + \eta[R/(\rho - \alpha)]$$
(A.2.3)

where k is a constant to be determined and θ is the negative root of the characteristic equation $\Omega(\theta) = (1/2)\sigma^2\theta(\theta - 1) + \alpha\theta - (\rho + \lambda) = 0.$

At the critical threshold value, $g(\overline{R}^q)$, optimality requires that the following *value-matching* and *smooth-pasting* conditions hold:

$$V^{q}(R^{q};\overline{R}^{q}) = P, \ \partial V^{q}(R;\overline{R}^{q})/\partial R\big|_{R=g(\overline{R}^{q})} = 0$$
(A.2.4-A.2.5)

¹⁴The solution for the homogeneous part of Eq. (A.2.1) should have the form $V_h^q(R) = k_1 R^{\theta_1} + k_2 R^{\theta_2}$ where k_1 and k_2 are constants to be determined while $\theta_1 > 0$ and $\theta_2 < 0$ are the roots of the characteristic equation $\Omega(\theta) = 0$. However, as $R \to \infty$, the value of the option to develop goes to zero. Thus, as $\theta_1 > 0$, then k_1 must be zero, otherwise $\lim_{R\to\infty} V_h^q(R) = \infty$.

Solving the system [A.2.4-A.2.5] yields:

$$k = \{P - \beta [P - \overline{R}^q / (\rho - \alpha)] (g(\overline{R}^q) / \overline{R}^q)^{\gamma} + \eta [g(\overline{R}^q) / (\rho - \alpha)] \} (1/g(\overline{R}^q))^{\theta}$$
(A.2.6)

and

$$\beta[(\theta - \gamma)/(\theta - 1)][P - \overline{R}^q/(\rho - \alpha)](g(\overline{R}^q)/\overline{R}^q)^\gamma + \eta[g(\overline{R}^q)/(\rho - \alpha)] - [\theta/(\theta - 1)]P = 0 \quad (A.2.7)$$

A.2.1 Naïve beliefs

Substituting q = n, $g(\overline{R}^n) = R^n$ and $\overline{R}^n = R^*$ into Eq. (A.2.6) and Eq. (A.2.7) yields:

$$k = \{P - \beta [P - R^*/(\rho - \alpha)](R^n/R^*)^{\gamma} - \eta [R^n/(\rho - \alpha)]\}(1/R^n)^{\theta}$$

and

$$\beta[(\theta - \gamma)/(\theta - 1)][P - R^*/(\rho - \alpha)](R^n/R^*)^{\gamma} + \eta[R^n/(\rho - \alpha)] - [\theta/(\theta - 1)]P = 0$$

Plugging k into Eq. (A.2.3) gives Eq. (8).

A.2.2 Sophisticated beliefs

Substituting q = s and $\overline{R}^n = \widetilde{R}$ into Eq. (A.2.6) and Eq. (A.2.7) yields:

$$k = \{P - \beta [P - \widetilde{R}/(\rho - \alpha)](g(\widetilde{R})/\widetilde{R})^{\gamma} - \eta [g(\widetilde{R})/(\rho - \alpha)]\}(1/g(\widetilde{R}))^{\theta},$$

and

$$\beta[(\theta - \gamma)/(\theta - 1)][P - \widetilde{R}/(\rho - \alpha)](g(\widetilde{R})/\widetilde{R})^{\gamma} + \eta[g(\widetilde{R})/(\rho - \alpha)] - [\theta/(\theta - 1)]P = 0.$$

Then, imposing the stationarity condition $g(\widetilde{R}) = \widetilde{R} = R^s$ yields:

$$k = \{P - \beta [P - R^{s}/(\rho - \alpha)] - \eta [R^{s}/(\rho - \alpha)] \} (1/R^{s})^{\theta},$$

and

$$R^{s} = \frac{\theta + \beta(\gamma - \theta)}{\eta(\theta - 1) + \beta(\gamma - \theta)} P(\rho - \alpha).$$

Plugging k into Eq. (A.2.3) gives Eq. (11).

A.3 Timing thresholds: Properties

Define the function $Z(x) = \beta[(\theta - \gamma)/(\theta - 1)][P - R^*/(\rho - \alpha)](x/R^*)^{\gamma} + \eta[x/(\rho - \alpha)] - [\theta/(\theta - 1)]P$. Note that Z(x) is convex in x, $Z(R^n) = 0$ and $Z(R^*) < 0$. Optimality requires that $Z'(R^n) > 0$. Hence, it follows that $R^* < R^n$. Then, as $\theta > \gamma$, it can easily be shown that $[\gamma/(\gamma - 1)] < [\theta + \beta(\gamma - \theta)]/[\eta(\theta - 1) + \beta(\gamma - \theta)] < [\theta/(\theta - 1)]$. This in turn implies that $R^* < R^s < R^{**}$.

Finally, define the function $Z(x;\tilde{x}) = \beta[(\theta - \gamma)/(\theta - 1)][P - \tilde{x}/(\rho - \alpha)](x/\tilde{x})^{\gamma} + \eta[x/(\rho - \alpha)] - [\theta/(\theta - 1)]P$. Denote by $g(\tilde{x})$ the solution of the equation $Z(g(\tilde{x});\tilde{x}) = 0$. Totally differentiating with respect to \tilde{x} yields:

$$\beta[(\theta - \gamma)/(\theta - 1)]\{-1/(\rho - \alpha) + [P - \tilde{x}/(\rho - \alpha)][(1/g(\tilde{x}))\partial g(\tilde{x})/\partial \tilde{x} - (\gamma/\tilde{x})]\}(g(\tilde{x})/\tilde{x})^{\gamma} + \eta(\partial g(\tilde{x})/\partial \tilde{x})/(\rho - \alpha) = 0$$

Rearranging gives:

$$\partial g(\widetilde{x})/\partial \widetilde{x} = \frac{\beta[(\theta - \gamma)/(\theta - 1)](g(\widetilde{x})/\widetilde{x})^{\gamma}\widetilde{x}(\gamma - 1)}{\beta[(\theta - \gamma)/(\theta - 1)][P(\rho - \alpha) - \widetilde{x}](g(\widetilde{x})/\widetilde{x})^{\gamma - 1} + \eta \widetilde{x}}(\frac{R^*}{\widetilde{x}} - 1) < 0, \text{ for } R^* < \widetilde{x}$$

Note that:

$$Z(R^n; R^*) = Z(R^s; R^s) = 0$$

Hence, as $R^* < R^s$, it follows that $R^n < R^s$.

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