



Maximum heat ratio: bi-directional method for fast and slow sap flow measurements

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Abstract

Background As sap flow research expands, new challenges such as fast sap flows or flows co-occurring with freeze/thaw cycles appear, which are not easily addressed with existing methods. In order to address these new challenges, sap flow methods capable of measuring bidirectional, high and slow sap flux densities (F_d , $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$), thermal properties and stem water content with minimum sensitivity to stem temperature are required.

Purpose In this study we assessed the performance of a new low-power ratio-based algorithm, the maximum

heat ratio (**MHR**) method, and compare it with the widely known heat ratio (**HR**) method using a cut-tree study to test it under high flows using *Eucalyptus grandis* trees, and a freeze/thaw experiment using *Acer saccharum* trunks to test its response to fast changing stem temperatures that result in freeze/thaw cycles.

Results Our results indicate that MHR and HR had a strong ($R^2=0.90$) linear relationship within a F_d range of 0–45 $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$. Using the MHR algorithm, we were able to estimate wood thermal properties and water content, while extending the measuring range of HR to approximately 0–130 ($\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$). In our freeze/thaw experiment, the main discrepancy between MHR and HR was observed during freezing, where HR had consistently lower F_d (up to 10 $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$), with respect to MHR. However, both algorithms identified similar zero flows.

Conclusion Consequently, MHR can be an easy-to-implement alternative algorithm/method capable of handling extreme climatic conditions, which can also run simultaneously with HR.

Keywords Maximum heat ratio · Thermal diffusivity · Volumetric water content · Freeze/thaw cycles · Volumetric heat capacity

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Introduction

As various sap flow methods move into extreme environments, new measuring challenges such as very fast

flows, or flows accompanied with fast stem temperature changes that result in freeze/thaw cycles appear. Coincidentally, these challenges are common in remote locations, where low-power sap flow methods, capable of measuring fast, slow, zero, and reverse flows are ideal. In general terms, there are two categories of commonly used thermometric sap flow sensors: heat dissipation (**HD**) (Clearwater et al. 1999; Granier 1985) and heat pulse (**HP**) methods (Cohen et al. 1981; Marshall 1958; Swanson 1962), which refers to the way the heat is released into the conductive tissue (i.e., sapwood) to monitor sap flow, and also defines their power consumption (pulse-based methods often having the least power requirements). Two of the common variations within the HP methods include the **Tmax** (Cohen et al. 1981) and the heat ratio (**HR**) (Burgess et al. 2001). Both the Tmax and HR methods are improvements from previous methods, and due to their working principles and the data they require, each exhibit optimal performance and accuracy within different ranges of sap flux densities (F_d , $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$) with high accuracy; Tmax for fast, and HR for slow, zero and reverse F_d . Of these two, only the HR method is capable of measuring positive (towards the canopy) and negative (towards the roots) flows, and because of its low-power requirements, it is ideal for extreme environments (e.g., plantations of fast-growing species, sites at high latitudes) where maintenance is difficult due to site accessibility. However, because of the working principle of the HR method, which requires a 60-s waiting period after the heat pulse to trace sap flow (Burgess et al. 2001), this method tends to fail at high flows since under these conditions the measurement period does not effectively capture the effects of heat convection on the heat pulse released into the sapwood. The relatively recently developed dual method approach (DMA, Forster 2019, 2020), addresses this issue by estimating F_d with both HR and Tmax methods, and outputs F_d from HR if conduction is less than convection, and F_d from Tmax if conduction exceeds convection. Table 1 shows the entire nomenclature used in this study.

Although HR, Tmax or DMA are referred to as separate methods, in essence they are simply alternative data processing algorithms used to infer heat pulse velocity (V_h , cm h^{-1}) and F_d from temperature measurements following the heat conduction–convection equation (Carslaw and Jaeger 1947; Marshall 1958; Vandegehuchte and Steppe 2012b):

$$\rho c \frac{\partial T}{\partial t} = \left[\frac{\partial}{\partial x} \left(K_{ax} \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(K_{ay} \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(K_{az} \frac{\partial T}{\partial z} \right) \right] - \rho c V_c \frac{\partial T}{\partial t} + P \quad (1)$$

which defines the way a pulse of heat propagates inside an anisotropic medium, which expressed in terms of temperature changes at a positive (up = ΔT_u , °C) or negative (down = ΔT_d , °C) distance from the heater source perpendicular to the sap flow (Fig. 1-a,b), yields:

$$\Delta T_u = \frac{q}{4\pi K t} \text{Ei} \left(\frac{\rho c (x_u + V_h t)^2}{4K t} \right) \quad (2)$$

$$\Delta T_u = \frac{q}{4\pi K t} \text{Ei} \left(\frac{\rho c (x_u - V_h t)^2}{4K t} \right) \quad (3)$$

Also expressed assuming an isotropic medium (i.e., equal K in the axial and tangential directions):

$$\Delta T = \frac{q}{4\pi K t} \text{Ei} \left(\frac{\rho c (x - V_h t)^2}{4t K} \right) \quad (4)$$

where q is the power released by the heater per unit length (W m^{-1}), ρc is the volumetric heat capacity of the green wood ($\text{J m}^{-3} \text{K}^{-1}$), K the thermal conductivity ($\text{W m}^{-1} \text{K}^{-1}$), V_h the heat pulse velocity, differentiated to zero and Ei the exponential integral. Due to previous data storage and data processing limitations (e.g., the first computing algorithm for Ei appeared a decade later) (Cody and Thacher 1968), attempts have been made to simplify Eq. 2 or to select specific points within the ΔT curve (Fig. 1-a) that allow to estimate V_h and F_d with minimal computing power. One of these attempts was the Tmax method, which is based on the property of the ΔT curve, that when the maximum ΔT (t_m) occurs, its slope is also zero. At this particular point, it is possible to ignore the first term of Eq. 2, and only the thermal diffusivity (D , $\text{m}^{-2} \text{s}^{-1}$) and the distance to the heater source (x , m) become relevant to estimate the heat pulse velocity using (Cohen et al. 1981):

$$V_h = \sqrt{\frac{x^2 - 4D t_m}{t_m}} \quad (5)$$

which additionally, under conditions of zero convective heat transport, D can be estimated using:

$$D = \frac{x^2}{4t_m} \quad (6)$$

Or with:

Table 1 Nomenclature and their use

Symbol	Units	Explanation & use
ΔT	$^{\circ}\text{C}/\text{K}$	Changes in temperature, usually after the heat pulse. Note that due to the linearity between $^{\circ}\text{C}$ and Kelvin, any ΔT can be expressed in $^{\circ}\text{C}$ or Kelvin
t_m	seconds	Time at which maximum ΔT occurs. In Eq. 6 it can be entered in hours
ΔT_u	$^{\circ}\text{C}/\text{K}$	ΔT at a positive (up) position from the heater
ΔT_d	$^{\circ}\text{C}/\text{K}$	ΔT at a negative (down) position from the heater
T_u	$^{\circ}\text{C}$	T at a positive (up) position from the heater
T_d	$^{\circ}\text{C}$	T at a negative (down) position from the heater
q	W m^{-1}	Power released by the heater by unit length
P	W m^{-3}	External heat input
ρc	$\text{J m}^{-3} \text{K}^{-1}$	Volumetric heat capacity of sapwood
K	$\text{W m}^{-1} \text{K}^{-1}$	Thermal conductivity of sapwood
K_{ax}	$\text{W m}^{-1} \text{K}^{-1}$	Axial K
K_{tg}	$\text{W m}^{-1} \text{K}^{-1}$	Tangential K
K_{rd}	$\text{W m}^{-1} \text{K}^{-1}$	Radial K
t	seconds	Time before or after the heat pulse
x	meters	Distance from the heater to the measurement point. Note that x can be entered in cm in Eq. 5 and Eq. 6
x_u	meters	x at a positive (up) position from the heater
x_d	meters	x at a negative (down) position from the heater
V_h	cm h^{-1}	Heat pulse speed (velocity). Note than in Eq. 2, Eq. 3 and Eq. 4, V_h is in m s^{-1}
V_c	cm h^{-1}	V_h corrected for wounding
V_s	cm h^{-1}	Sap velocity
Ei		Exponential integral
D	$\text{m}^2 \text{s}^{-1}$	Thermal diffusivity of sapwood
V	Volts	Voltage applied to the heaters
R	Ω	Total resistance of the heater
R_L	Ωm^{-1}	R expressed in length
ρ_w	kg m^{-3}	Bulk density of the sapwood
ρ_s	kg m^{-3}	Bulk density of sap, assumed to be similar to density of water
θ_v	$\text{m}^3 \text{m}^{-3}$	Volumetric water content
c_w	$\text{J kg}^{-1} \text{K}^{-1}$	Specific heat capacity of sapwood
c_s	$\text{J kg}^{-1} \text{K}^{-1}$	Specific heat capacity of sap, assumed similar to water
F_d	$\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$	Sap flux density
D_s	0–1	Normalized sapwood depth
A_s	cm^2	Sapwood area
Q	Liters h^{-1}	Sap flow
GWU	Liters h^{-1}	Gravimetric water use

$$D = \frac{K}{\rho c} \quad (7)$$

When the V_h is slow, finding t_m in the ΔT curve is challenging and consequently Eq. 5 and Eq. 6 over or underestimate V_h and D , respectively. It was also proposed that the maximum T in a T_u - T_d (Fig. 1-c) curve also satisfied Eq. 5 (Cohen et al.

1981), but this approach is not sensitive to slow flows. An additional alternative to increase sensibility to slow and zero flows, while minimizing computing requirements, was to collect measurements above and below the heater (Fig. 1-a,b), to divide their respective equations (e.g., Eq. 2 and Eq. 3) (Burgess et al. 2001; Marshall 1958), which

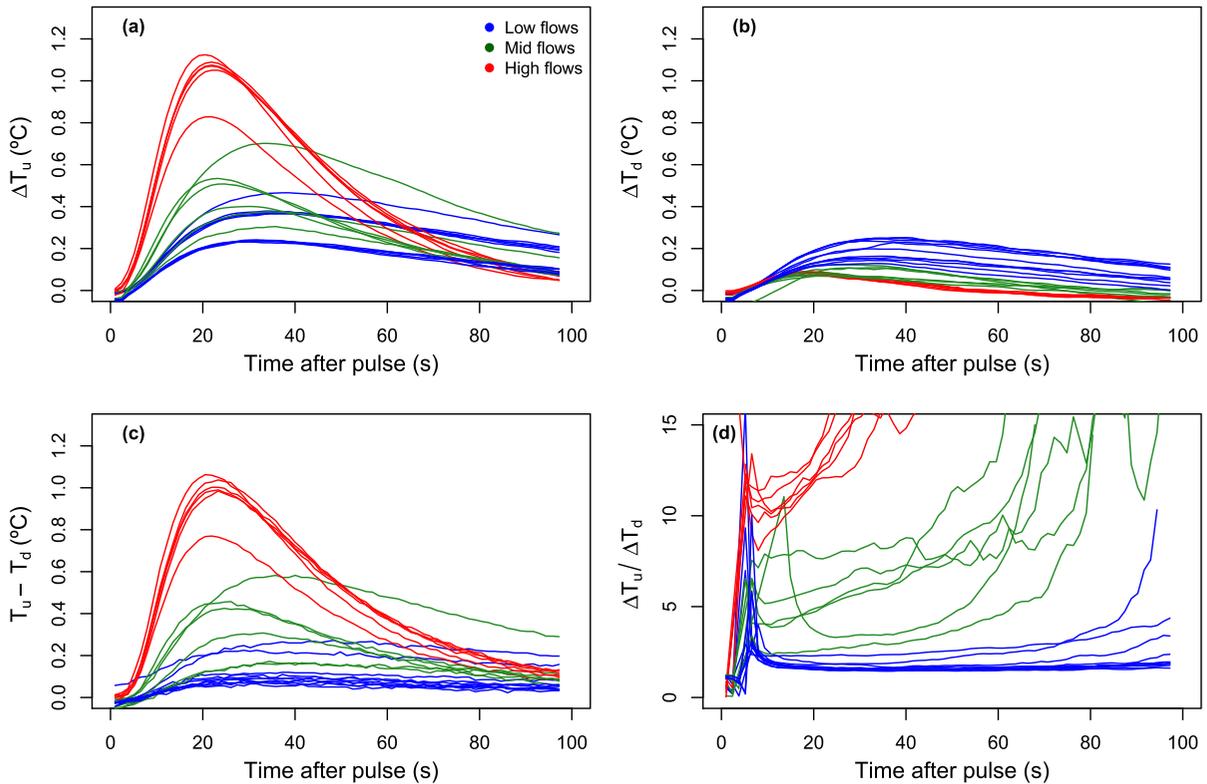


Fig. 1 Measurements used to estimate heat pulse velocity (V_h , cm h^{-1}) following a short (< 3 s) heat pulse. **(a, b)** Temperature increments in a probe at a positive (ΔT_u) and negative (ΔT_d) distance from a heater source. **(c)** Differential tem-

perature between T_u and T_d from the heater source. **(d)** Ratio between ΔT_u and ΔT_d . All data has been color-coded according to estimated F_d range: blue < 20, green 20–60, red > 60 $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$

eliminates the first component of the equations, resulting in:

$$\frac{\Delta T_u}{\Delta T_d} = Ei \left[\frac{(x_u + V_h t)^2 - (x_d - V_h t)^2}{4Dt} \right] \quad (8)$$

which solving for V_h yields:

$$V_h = \frac{2D}{x_u + x_d} \ln \left(\frac{\Delta T_u}{\Delta T_d} \right) + \frac{x_u - x_d}{2t} \quad (9)$$

Were if x_u and x_d are equidistant the last term can be ignored resulting in:

$$V_h = \frac{D}{x} \ln \left(\frac{\Delta T_u}{\Delta T_d} \right) 3600 \quad (10)$$

where D can be estimated using Eq. 6 or Eq. 7. The versatility of this equation is that it is not necessary to know the specific amount of heat released

by the heater. Additionally, this alternative makes it very easy to estimate zero flow. But as mentioned before, one consequence of this algorithm is that the $\Delta T_u/\Delta T_d$ curve becomes unstable during fast flows, primarily because ΔT_d approaches zero. However, independently of the algorithm used to estimate V_h , any sensor capable of generating both ΔT_u and ΔT_d curves, can be used to estimate: F_d with both HR and Tmax methods, thermal properties such as K and ρc , and volumetric water content (see details below for how thermal properties such as ρc , can be used to estimate volumetric water content), provided the right data are collected. The challenge is to select the point or points in the $\Delta T_u/\Delta T_d$ curve that satisfy Eq. 9 and Eq. 10. More specifically, the challenge is to identify the $\Delta T_u/\Delta T_d$ data points, that maintain a linearity with F_d as V_h increases. Marshall (1958) provided the theoretical background to show that overall $\Delta T_u/\Delta T_d$ satisfies Eq. 10, but there were nearly no further

developments (see: Hogg and Hurdle 1997). Burgess et al (2001) selected the mean from 60–100 s after the pulse within the $\Delta T_u/\Delta T_d$ curve (mainly because it is fairly linear within this range) and proposed the now widespread method/algorithm known as the heat ratio method (HR) that has shown high precision within F_d from -45 to $+45$ ($\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$).

Consequently, there is no universally-accepted sap flow method, most are prone to technical complications, and rely on calibrations to improve measurement accuracy (Flo et al. 2019; Swanson 1994; Vandegehuchte and Steppe 2013). For example, HD methods (e.g., Granier 1985) can result in significant underestimations of F_d (up to 60%) (Cabibel and Do 1991; Flo et al. 2019; Lu and Chacko 1998; Lundblad et al. 2001; Steppe et al. 2010; Sun et al. 2012). But after calibration, HD performs equally, or better than HP methods, especially at fast F_d ranges (Gutierrez Lopez et al. 2018; Gutiérrez Lopez et al. 2018). Consequently, the selection of sap flow methods is often based on method complexity, cost, power use and associated stand-alone time (i.e. the time n sensors can be powered out of a rechargeable battery), and more importantly, the expected ranges of F_d to be measured. Method complexity in particular, has helped HD methods (Clearwater et al. 1999; Granier 1985) become more popular, compared to heat pulse methods which require more complex programming for data collection and processing. However, with the widespread availability of large-memory storage devices, storing entire ΔT curves to run any algorithm on Eq. 4 to estimate simultaneously V_h , F_d , wood thermal properties, and volumetric water content is currently more viable.

Sap flow research has become a fundamental part of studies seeking to understand responses of individual plants, whole stands and ecosystems, to abiotic and biotic drivers (Alvarado-Barrientos et al. 2013; Eller et al. 2015; Kagawa et al. 2009; Kukowski et al. 2013; Lundblad and Lindroth 2002; Meinzer et al. 2004; Steppe et al. 2006; Vergeynst et al. 2014; Zalesny et al. 2006). In physiological studies, sap flow measurements can help identify the underlying mechanisms that explain changes in water movement along the soil–plant–atmosphere continuum at the individual plant scale. In ecological studies, sap flow measurements help examine the responses of ecosystem processes and functions related to water use and cycling to environmental change (e.g., disturbance, drought,

nutrient amendments, etc.). In both ecological and physiological studies, HP methods capable of measuring slow, zero and reverse flows (i.e., HR method) receive overall less attention, in part because most studies focus primarily on transpiration-induced sap flow, where the vast majority of the flow is positive. Methods capable of measuring bidirectional flows are then ideal in studies interested in hydraulic redistribution in roots (Burgess et al. 2000), foliar water uptake (Schreel and Steppe 2019), studies focused on non-transpiration sap flow, or studies where tree transpiration occurs when stem temperature crosses the freezing point of sap, where both positive and negative flows need to be accounted for (Cienciala et al. 1999; Gutierrez Lopez et al. 2021; Hasper et al. 2016; Kozii et al. 2020; Lagergren and Lindroth 2002). In environmental conditions that result in fast bidirectional flows, the equidistant placement of temperature-monitoring probes around the heater source, HR and other bidirectional methods offer a greater advantage at identifying periods of time when sap flow is zero or reverse. In traditional unidirectional HD methods (i.e. Clearwater et al. 1999; Granier 1985) an equilibrium period overnight is required to determine zero flow, and since this is often hard to achieve, this has become the subject of extensive research (Bush et al. 2010; Do and Rocheteau 2002; Forster 2017; Oishi et al. 2016; Peters et al. 2018; Rabbel et al. 2016; Regalado and Ritter 2007; Vergeynst et al. 2014), often involving as much computing power as HP methods.

Alternatives to HD and HP methods (e.g., Tmax, HR) exist, such as the Sapflow + or the DMA, which can account for changes in volumetric water content in the sapwood, albeit no details are available on how the later estimates stem water content (Forster 2019, 2020). However, at this time their application is limited. The Sapflow + method (Vandegehuchte and Steppe 2012b) uses four probes to estimate F_d . While it is advantageous, because it estimates sapwood water content, and accounts for anisotropic thermal properties, for ecological studies, it is important to consider the possible limitations created by increasing the number of probes per sensor (which might limit sample size) and increase wounding effects, as shown in similar methods (Burgess et al. 2001). The DMA is a recently published algorithm that requires the estimation of F_d with both Tmax and HR methods, and estimate the ratio between heat conduction

and convection to decide which F_d is reported. These additional data processing requirements might discourage new users. DMA is arguably a good alternative to extend the measuring range of HR, however the effects of switching from a ratio to a non-ratio method remains to be more widely tested, particularly given each method will have its own relationship to the theories and practice of wound correction and adjustment for wood thermal properties (see previous discussion on how V_h is estimated with Tmax and HR methods using Eq. 5 and Eq. 10, respectively). Another alternative is the compensation heat pulse (CHP) method, which has been validated under field and laboratory conditions (Fernandez et al. 2006; Poblete-Echeverria et al. 2012; Vandegehuchte et al. 2015), however, this method is also known to perform poorly at slow F_d ranges (Becker 1998; Burgess et al. 2000).

Consequently, increasing the measuring range of the already validated HR method (initially estimated to be from -55 to $+55$ $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$, when D is approximately $2 \times 10^{-7} \text{m}^2 \text{s}^{-1}$) is then of great interest for ecological and physiological studies, which could additionally eliminate the need to use various methods to make comparisons while providing the advantages of a low-powered method. To our knowledge, only one study (Vandegehuchte et al. 2015) has experimented with the data analysis algorithm of HR and studied how changes in diel stem temperature affect F_d measurements, but no analysis were performed below the freezing point of sap. According to their results, estimating the ratio at different time intervals within the $\Delta T_u/\Delta T_d$ curve after the heat pulse (compared to the standard 60–100 s after the pulse), increases the measuring range of F_d , but we are not aware if validations of any additional algorithms to extend the measuring range of HR have been published.

In this study, we tested and validated a new data analysis algorithm that is based on a similar data collection and processing routine to the HR method, which we call the maximum heat ratio (MHR) algorithm. The MHR algorithm is an alternative to extend the measuring range of HR, that we show is similar to F_d estimates derived from the HR method (within its measuring range), and also matches high flows estimated by Tmax methods (known for their reliability at high flows). Additionally, we show the process to estimate thermal properties and volumetric water

content when ΔT_u and ΔT_d curves are available. We conducted a validation in two experiments, (a) a cut-tree experiment using eight one-year-old *Eucalyptus grandis* Hill ex Maiden trees and (b) a freeze/thaw experiment using two freshly harvested *Acer saccharum* Marshall trunks. The overarching goal of this study was to test and validate the new MHR algorithm, establish its measurement range, and test its performance on high flows and extreme environmental conditions, especially when the stems often cross the freezing point of sap, to assess the effects of K and ρc on F_d estimates. To our knowledge, no previous studies have assessed and validated whether alternative temperature ratios can be used to estimate high F_d . In sap flow research a low-power ratio-based method capable of measuring high and low F_d at high precision and accuracy, is highly desirable, but so far, no method seems to perform satisfactorily under contrasting F_d ranges. Finally, studies that have previously collected raw data to estimate F_d using the HR method, might benefit from the extended measuring range of MHR algorithm, if HR was unable to estimate high flows.

Materials and methods

Cut-tree experiment set up

We used a total of eight one-year-old trees ranging from 3–6 cm in diameter (See Table 2), harvested at a local plantation, inside the installations of the National Agricultural Technologies Institute (INTA)

Table 2 Diameters of trees and trunks used in the cut-tree, and freeze/thaw experiments

Tree/log	Species	Diameter (cm)	Harvest date/time
1	<i>E. grandis</i>	5.3	May 1 2015, ~ 8:00
2	<i>E. grandis</i>	6.1	May 1 2015, ~ 8:00
3	<i>E. grandis</i>	3.9	May 1 2015, ~ 9:00
4	<i>E. grandis</i>	6.1	May 1 2015, ~ 12:00
5	<i>E. grandis</i>	4.3	May 1 2015, ~ 12:00
6	<i>E. grandis</i>	6.1	May 3 2015, ~ 13:00
7	<i>E. grandis</i>	5.6	May 3 2015, ~ 13:00
8	<i>E. grandis</i>	5	May 3 2015, ~ 15:00
1	<i>A. saccharum</i>	15	Dec 10 2017
2	<i>A. saccharum</i>	18	Dec 10 2017

in Concordia, Argentina in 2015 (DOY 123–128). Small trees were selected due to their higher leaf area (Almeida et al. 2007; Forrester et al. 2010) and higher leaf area/sapwood area ratios, which result in fast F_d . Gravimetric water use (GWU, Liters h^{-1}) was estimated for each tree at 15-min intervals from 6AM–8PM using a modified cut-tree experiment. (for further details, see: Gutiérrez Lopez et al. 2018). All tree stems were covered with a reflective insulation wrap (ISOLANT 5 mm), and sensors were installed in different cardinal directions across the individual trees (two replicates per cardinal direction). Air temperature and relative humidity were monitored with a HMP50 sensor (Campbell Scientific Inc., Logan, UT, USA).

Freeze/thaw experiment

Two 40 cm long, approximately 15 cm DBH *Acer saccharum* trunks were harvested near the University of New Hampshire campus, in Durham, NH in 2017. Both trunks were sealed with wax and Parafilm on both ends, and each trunk was instrumented with a HP sensor, with equidistant measuring probes, located at 0.5 cm from the heater, with three measuring points at 0.5, 1.65 and 3 cm into the sapwood. The freeze/thaw cycles applied to *A. saccharum* trunks were performed with a commercial freezer that was kept at $-16\text{ }^\circ\text{C}$. The trunks were placed inside the freezer every night after ~ 19 h and were removed the following morning (~ 8 h) to allow them to warm up at room temperature (26°C). We also collected data when the trunks were continuously at lower than -10°C or more than 20°C for more than 24 h, but we focused on periods with fast freeze/thaw cycles.

Equipment set up and data collection

We used CRBasic 3.8.1 (Campbell Scientific Inc.) to write all scripts needed for data collection (available at <https://github.com/joseagl/MHR>). Data loggers (CR1000, Campbell Scientific Inc.) and multiplexers (AM1632B, Campbell Scientific Inc.) were used to read and store data for both experiments. All sap flow sensors were connected using low voltage double-shielded cables (75985K63-Mcmaster), and thermocouple cables (TFCC-005–100-Omega), which were extensions to Type-T thermocouples inserted in the temperature sensing probes. The heaters of the HP

sensors build out of coiled 36G nichrome wire, had a total resistance of $\sim 19\ \Omega \pm 0.2$ and were connected in parallel and controlled with a custom-designed solid-state relay circuit with a maximum current limit of 4 amperes (for further details, see: Gutiérrez Lopez et al. 2018). The cut-tree experiment was powered with a 12 V 105Ah lead-acid battery, and the freeze/thaw experiment with a 12 V 12Ah lead-acid battery. According to our calculations, the total power released by the heaters (q) was $\sim 168\ \text{W m}^{-1}$, calculated as:

$$q = \left(\frac{V}{R}\right)^2 R_L \quad (11)$$

where V is the voltage (volts) applied to the heaters, measured after the relay circuits, R the entire resistance of the heater ($\sim 19\ \Omega$), R_L the resistance expressed per length ($\Omega\ \text{m}^{-1}$). Temperature (T , $^\circ\text{C}$) of each of the six thermocouples per sensor was recorded at a scan rate of ~ 1.5 s for 143 consecutive seconds, at 15-min intervals. The full measurement period, or individual data series, consisted of 30 s of consecutive measurements of initial temperature, followed by a 3 s heat pulse, and ending with 110 s of consecutive temperature measurements (94 temperature data points per data series).

Data processing

All of the data were processed with custom-designed scripts developed in R 3.6.3 (R Core Team, Vienna, Austria) that allowed us to estimate V_h , F_d and total sap flow (Q , L h^{-1}) for both methods. The entire MHR algorithm was implemented on both cut-tree and freeze/thaw data as follows: we first estimated the slope of the initial 30 s of temperature readings, ignoring the first and last 4 s to discard potential equilibration period, or memory effects. This was considered the stem temperature trend, and initially all consecutive temperature measurements within a data series were detrended, but unlike similar studies (Vandegehuchte et al. 2015), detrending all data series resulted in additional noise, and consequently we decided not to detrend our data series. Next, we estimated mean temperature for the initial 30 s, and this mean was subtracted from all measurements within the data series to estimate actual temperature increment (ΔT , $^\circ\text{C}$). Once each ΔT curve was estimated, all measurements were

run through a simple loess function (Cleveland 1979, 1981) at a span of 0.15. Once the loess function was estimated, we predicted the ΔT curve at a 5 Hz resolution (i.e., 5 data points per second), and applied a similar process all six thermocouples (three up ΔT_u , and three down ΔT_d from the heating source) inside the stem. For clarification purposes, in Fig. 1 we show the main temperatures, temperature differentials and temperature ratios proposed or used in various heat pulse methods, where ΔT_u is the temperature change after the pulse, at a positive (or negative ΔT_d) distance from the heater, $T_u - T_d$ the differential temperature, and $(\Delta T_u / \Delta T_d)$ the ratios of temperature changes after the pulse. To estimate the temperature ratio $(\Delta T_{\max_u} / \Delta T_{\max_d})$ we divided the maximum ΔT_{\max_u} after the heat pulse (see: Fig. 2-A), over the maximum ΔT_{\max_d} of the corresponding lower probe (see: Fig. 2-B). Since both ΔT_{\max} rarely occur after 50 s of the heat pulse even at very fast flows ($F_d > 100 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$), we fixed the timeframe to find ΔT_{\max} between 0–50 s after the pulse. To show that MHR ratios remain stable at fast flows, we divided the ΔT_{\max_u} over every ΔT_d after the heat pulse and compared it with the traditional HR

method ratios (see: Fig. 2-C&G). Next, we used the ΔT_u data after the pulse, and solved Eq. 4 for ρc and K , and estimated D according to Eq. 7. While V_h can also be extracted fitting Eq. 4, we limited the curve fitting to ρc and K only to avoid overfitting (Lever et al. 2016). Simultaneously ρc was used to estimate sapwood volumetric water content ($\theta_v, \text{m}^3 \text{ m}^{-3}$), see below for details. Once the temperature ratio $(\Delta T_{\max_u} / \Delta T_{\max_d})$ and D were estimated, heat pulse velocity ($V_h, \text{cm h}^{-1}$) was estimated with Eq. 10 (where ΔT_u and ΔT_d were the ΔT_{\max_u} and ΔT_{\max_d} , respectively) and corrected for wounding ($V_c, \text{cm h}^{-1}$) according to Burgess et al. (2001) using the following equation where b , c , and d , are the wounding parameters:

$$V_c = bV_h + cV_h^2 + dB_h^3 \quad (12)$$

We also note that because wound correction functions were originally derived for the HR method, we plan in future works to examine wound correction functions specifically for the MHR; in the meantime we note however, that the two algorithms are closely correlated over a considerable common range. V_c was converted

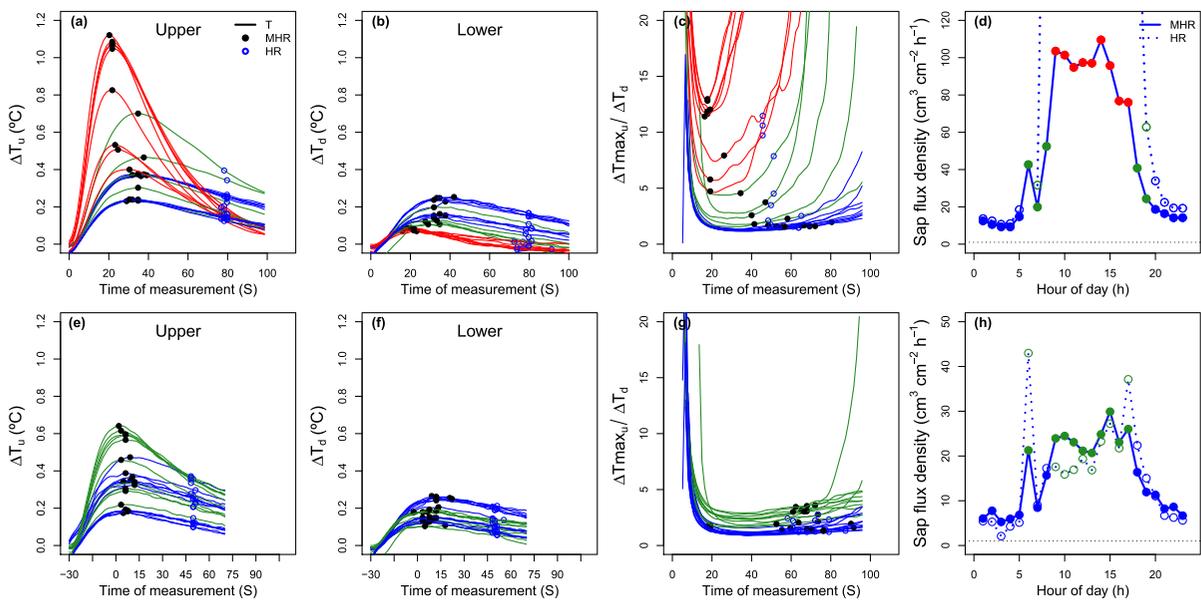


Fig. 2 Use of the maximum heat ratio (MHR) algorithm. For visualization purposes, ΔT ($^{\circ}\text{C}$) have been color-coded within different F_d ranges (blue < 20 , green $20\text{--}60$, red $> 60 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$). **a**: temperature increments (ΔT , $^{\circ}\text{C}$) before and after the heat pulse in the upper probe, **b**: ΔT ($^{\circ}\text{C}$) in the lower probe, **c**: temperature ratios obtained when the maximum ΔT in the upper probe, is divided over each ΔT in the lower probe

(After the pulse only, $R_T > 30$ and < 1 were ignored). The black circles correspond to the R_T estimated using MHR and blue open circles correspond to HR. **d**: Sap flux density (F_d , $\text{cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$) estimated with temperature ratios obtained using MHR and HR methods. In the bottom panels (**e**, **f**, **g**, **h**) we show the same process, but for a sensor with a lower range of sap flux densities (within the measurement range of HR)

to F_d according to Vandegehuchte and Steppe (2013) using:

$$F_d = \frac{\rho_w}{\rho_s} \left(\theta_v + \frac{C_w}{C_s} \right) V_c \tag{13}$$

where ρ_w is the density of the sapwood (kg m^{-3}), ρ_s the density of water (kg m^{-3}), θ_v the volumetric water content of the sapwood ($\text{m}^3 \text{m}^{-3}$), C_w the specific heat capacity of sapwood ($\text{J kg}^{-1} \text{K}^{-1}$), and C_s the specific heat capacity of sap (assumed to be the same as water). F_d was estimated for both MHR and the traditional HR method by Burgess et al. (2001) (Fig. 2-D&H). To estimate θ_v , we used the estimated ρc (i.e., Eq. 4 for each ΔT_u curve and solving for K and ρc) and since θ_v is directly proportional to ρc (Campbell et al. 1991):

$$\rho c = c_s \rho_s \theta_v + c_w \rho_w \tag{14}$$

Solving for θ_v yields:

$$\theta_v = \frac{\rho c - \rho_w c_w}{\rho_s c_s} \tag{15}$$

Both K and ρc were estimated for each 15-min period as shown in Fig. 3, but D used in Eq. 10 was the value that corresponded to zero flow (zero F_d in Fig. 3-a-b). For $F_d > 0$, ρc used in Eq. 15, and subsequently in Eq. 13 were the 15-min interval estimates (Fig. 3). Finally, since we fitted Eq. 4 at three positions within the sapwood, we focused on D estimated in the outer depth at zero and slow flows, primarily because deeper positions rarely reached true zero flow during our study, consequently D used on other sapwood depths is considered an approximation. Each depth had its own θ_v estimated at 15-min intervals, although for most depths, θ_v remained relatively constant (see Fig. 3-e). To estimate whole tree water use (Q , L per hour) for both MHR and HR in the cut-tree experiment, we fitted the following radial profile equation to address the commonly known changes in F_d with sapwood depth (Berdanier et al. 2016; Caylor and Dragoni 2009; Granier et al. 1994; Wullschleger and King 2000):

$$F_d = \beta_0 (\beta_1 - \exp(-\beta_1 D_s)) * (\beta_0 * \exp(-\beta_2 D_s) * x + (\beta_3 - \beta_4 D_s)) \tag{16}$$

where D_s is the normalized sapwood depth, and $\beta_0, \beta_1, \beta_2, \beta_3$, and β_4 the parameters fitted for the

model. Sapwood depth was normalized and split into 100 bins, and we fitted the model across the three F_d estimates for each sapwood depth monitored. F_d and sapwood area (A_s , cm^2) were predicted for each of the 100 bins, and sap flow (Q , L h^{-1}) was estimated by integrating their product. A radial profile equation was fitted for every measurement time (i.e., 96 per day) for each tree and stem. All curve fitting process were performed in R 3.6.3 (R Core Team, Vienna, Austria) using the lme4 (Bates et al. 2015) and expint (Goulet 2016) packages. The freeze–thaw experiment focused on F_d only and no radial profiles were fitted.

Statistical analyses

To compare sap flux density estimates derived with MHR and HR algorithms, we focused on linear relationships. The first set of analysis focused on F_d whereby linear regressions and F-tests were performed between MHR and HR for each individual day of study (DOY: 123 through 128) and combining all the days, these were used to derive estimates of the ranges at which MHR and HR have a linear relationship. These analyses were performed for both cut-tree and freeze/thaw experiments. The second set of data analyses focused on sap flow (Q , L h^{-1}) estimated with MHR and HR, and their relationship to measured gravimetric water use (GWU , L h^{-1}). These analyses were also performed by day of study (DOY: 123 through 126) and combining all dates. All analyses were performed using base functions in R 3.6.3.

Results

Measurable F_d range of HR and MHR algorithms

Using data from our cut-tree experiment, we were able to measure a F_d range from 0–45 ($\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$) using the HR algorithm with a minimal presence of outliers, and a range of 0–130 ($\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$) using MHR on one-year-old *E. grandis* trees ranging from 3 to 6 cm in diameter (Fig. 4-b).

We did not observe significant under or overestimations of Q for each algorithm within these ranges

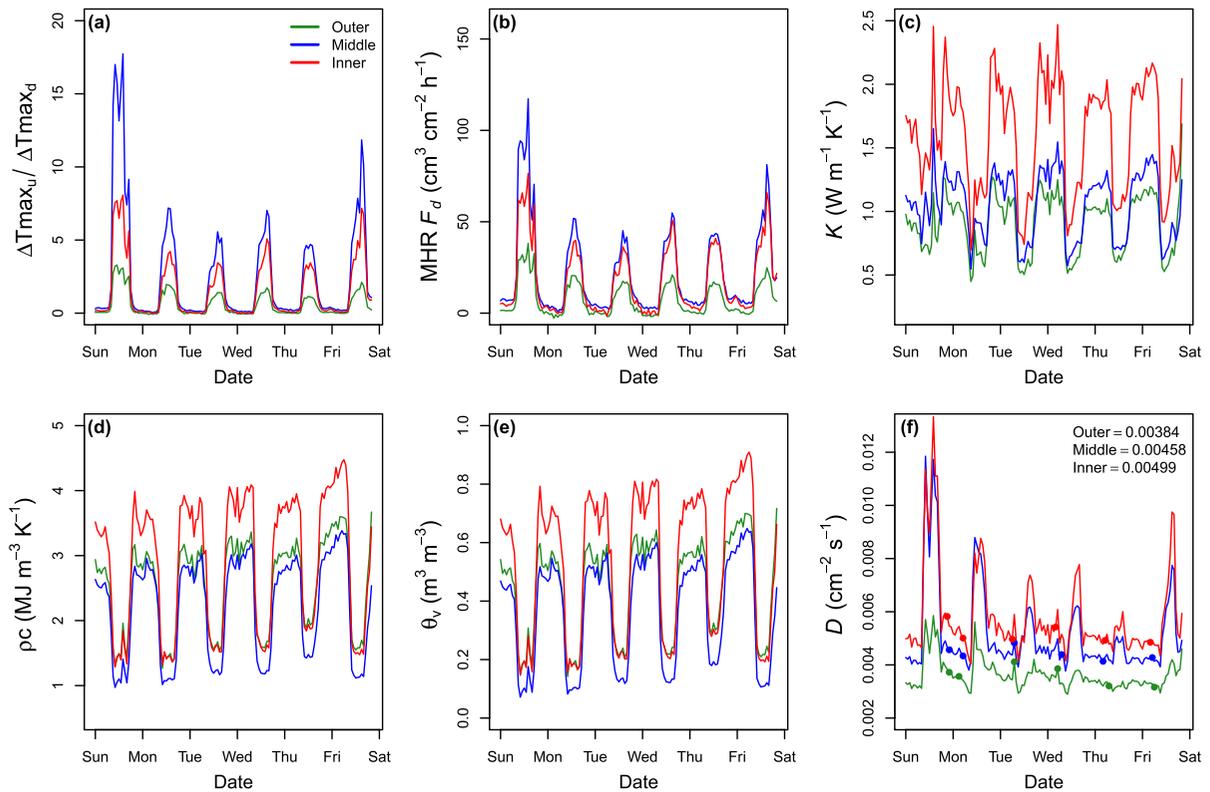


Fig. 3 a: Heat ratios ($\Delta T_{\max_u} / \Delta T_{\max_d}$), **b:** sap flux density (F_d , $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$) estimated using maximum heat ratio, **c:** thermal conductivity (K , $\text{W m}^{-1} \text{K}^{-1}$), **d:** volumetric heat capacity (ρc , $\text{MJ m}^{-3} \text{K}^{-1}$) and **e:** volumetric water content (θ_v , $\text{m}^3 \text{m}^{-3}$) and thermal diffusivity (D , $\text{m}^2 \text{s}^{-1}$) estimated for each

of the three sapwood depth positions (Outer, Middle, Inner) at 15-min intervals, shown as hourly means. Closed circles in **f**, highlight thermal diffusivity at times when sap flux density was zero. Data used in this graph corresponds to tree 2

when the instrumentation was functioning correctly (equipment malfunction resulted in underestimated Q on some trees on DOY 124–125; see discussion for further details). The maximum measurable F_d ranges estimated with MHR varied by tree, but it was often greater than $100 \text{ cm}^3 \text{cm}^{-2} \text{h}^{-1}$ (Fig. 4-b). Some trees showed a reduction in F_d from the first to the second day of our experiment. This reduction was in some cases close to 50%, for example Tree 2, reduced from $130 \text{ (cm}^3 \text{cm}^{-2} \text{h}^{-1}$, estimated with MHR) to around 60 from DOY 123 to DOY 124. Our analysis suggests that these reductions were not associated with hydraulic cavitation, in part because except for tree 8, θ_v showed a normal daily cycle on all trees (e.g. Figure 3-e).

Comparison between MHR and HR algorithms

An initial comparison between HR and MHR showed that ratios estimated with HR were noisier and had a higher number of aberrant positive and negative values (i.e., values with an absolute value greater than three standard deviations), especially at high transpiration rates (Fig. 4-B&C). Conversely MHR ratios appeared more stable, and we did not observe extremely high or negative values, especially when the F_d range was higher than $60 \text{ (cm}^3 \text{cm}^{-2} \text{h}^{-1}$). Estimated F_d derived from MHR and HR algorithms were similar within a range of $0\text{--}45 \text{ cm}^3 \text{cm}^{-2} \text{h}^{-1}$ ($R^2=0.90$, linear regression: $\text{HR} = 0.56 + 1.063 * \text{MHR}$. Figure 5a,b,c). Above this

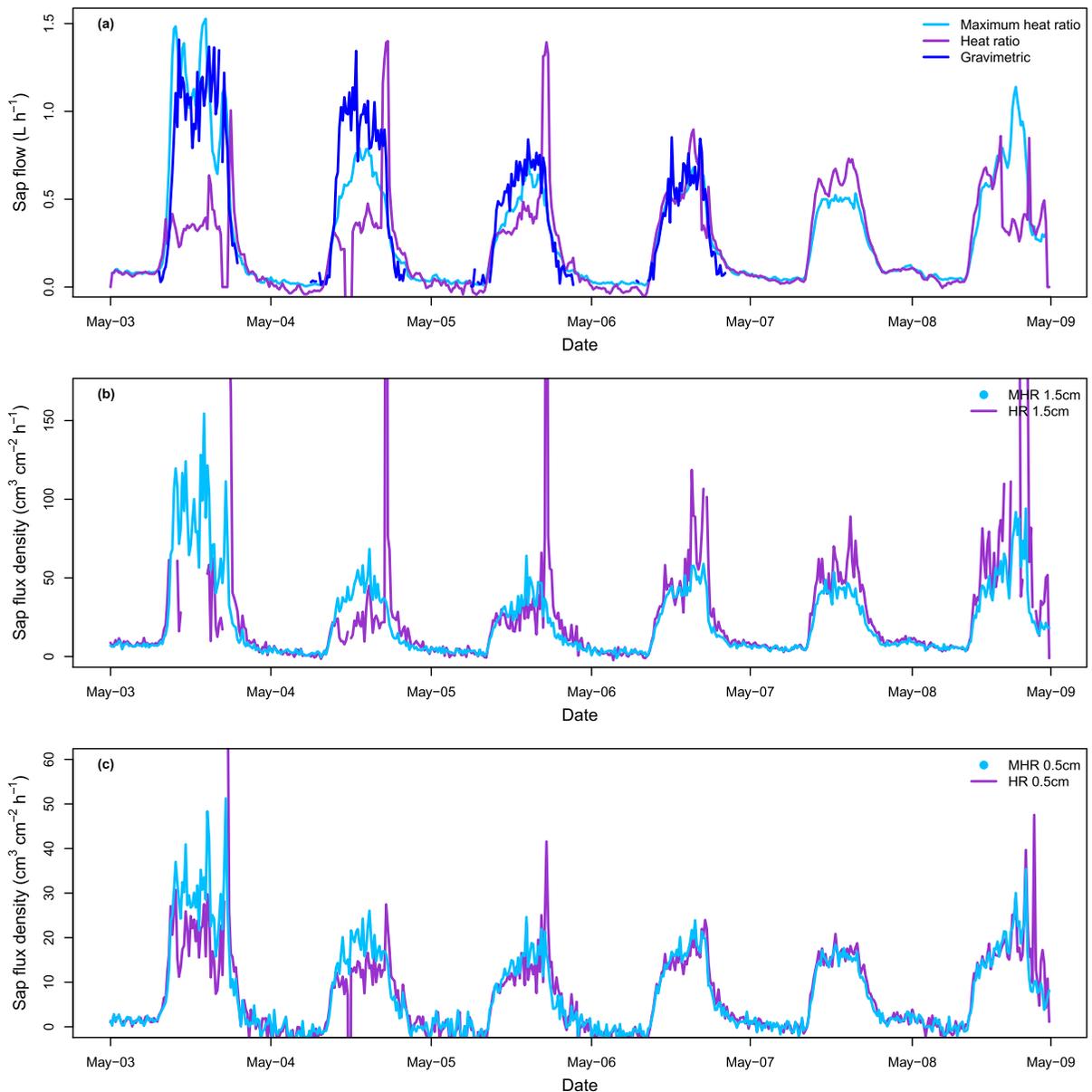


Fig. 4 Sap flow (Q , $L d^{-1}$) and sap flux density (F_d , $cm^3 cm^{-2} h^{-1}$) estimated with the maximum heat ratio (MHR) and heat ratio (HR) methods. **a:** sap flow (Q , $L h^{-1}$) estimated using the maximum heat ratio method (MHR) and the tradi-

tional heat ratio (HR) methods compared with gravimetric measurements, and sap flux density (F_d , $cm^3 cm^{-2} h^{-1}$) estimated with each method at 1.5 cm **b:** and 0.5 cm **c:** into the sapwood. Data used in this graph corresponds to tree 2

threshold, the F_d estimates differed significantly, mainly due to the abnormally high or low estimates of HR. The correlation between MHR and HR varied within each day, and except for the first day of our experiment, seemed to be driven by the rate change in VPD (i.e., the net VPD change from 6AM to max VPD). For example, on DOY 124, MHR and HR

were correlated within a shorter range (approx. 0–20 $cm^3 cm^{-2} h^{-1}$), compared DOY 126 (approx. 0–50 $cm^3 cm^{-2} h^{-1}$, Fig. 5).

Differences between MHR and HR were also dependent on the time of the day. From 0 to 12 h when F_d was lower than 40 $cm^3 cm^{-2} h^{-1}$, the correlation between HR and MHR was stronger

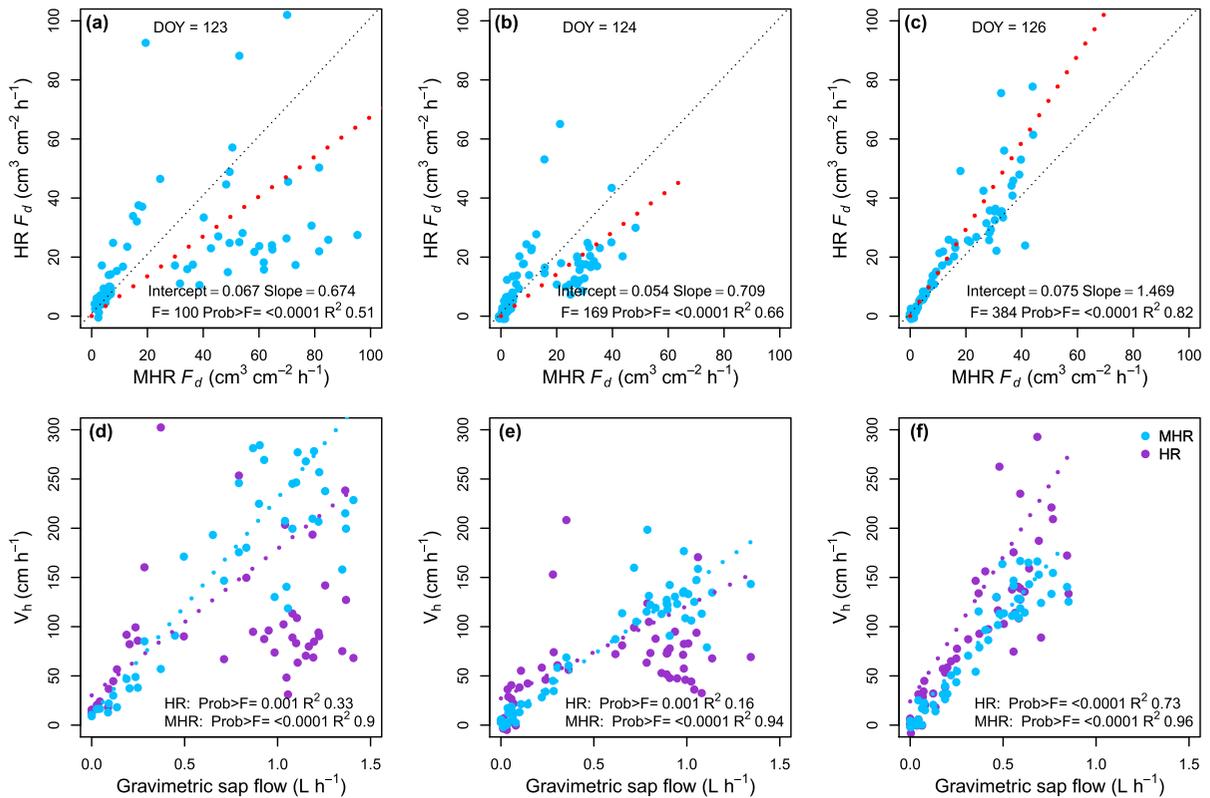


Fig. 5 **a, b, c:** Correlation of sap flux density (F_d , $\text{cm}^3 \text{cm}^{-2} \text{h}^{-1}$) estimates between maximum heat ratio (MHR) and heat ratio (HR) algorithms. Dotted red line represents the line of best fit between MHR and HR. **d, e, f:** Correlation between

mean heat pulse velocity (V_h , cm h^{-1}) across sapwood depths estimated with Eq. 10, and gravimetric water use (GWU, L h^{-1}). Data used in this graph corresponds to tree 2, and similar patterns were observed in other trees

($\text{HR} = -0.1303 + 1.074 * \text{MHR}$, $R^2 = 0.96$) than between 13–24 h ($\text{HR} = 2.192 + 1.02 * \text{MHR}$, $R^2 = 0.79$) (data not shown). Additionally, the HR algorithm showed an overestimation memory effect (average: $5 \text{ cm}^3 \text{cm}^{-2} \text{h}^{-1}$) with respect to MHR on the second half of the day (13–24 h) primarily in trees that had F_d greater than $\sim 50 \text{ cm}^3 \text{cm}^{-2} \text{h}^{-1}$. This memory effect was characterized by an overestimation where F_d that remain higher even after F_d returned to the measurable range of the HR method. However, since no overestimation was observed when F_d was lower than 50, this suggests that this memory effect occurs only when F_d falls outside the measurement range of HR. Finally, the MHR temperature ratio ($\Delta T_{\text{max}_u} / \Delta T_{\text{max}_d}$), and the V_h estimated from it using Eq. 10, showed a stronger linearity with GWU, compared with the temperature ratios and V_h from HR (Fig. 5-d, e, f).

Whole tree sap flow estimates (Q , L h^{-1}) from MHR and HR algorithms had similar patterns to those of F_d (Fig. 6), particularly at low water use rates. However, since Q is integrated from different annuli within the sapwood, and some annuli had F_d outside the measurable range of HR, the underestimation observed using HR was the result of missing values, caused by the limited F_d measurement range of this algorithm (as seen in Fig. 4-a). Consequently, HR showed underestimations of mean whole-tree sap flow when F_d was often outside the measuring range of HR. Overall, Q estimates from MHR had a higher correlation ($b_0 = 0.01$, $b_1 = 0.80$, $R^2 = 0.91$) with mean GWU compared to HR ($b_0 = 0.02$, $b_1 = 0.53$, $R^2 = 0.68$), with differences by day resulting from low Q estimates from HR. Due to power issues during DOY 124 and 125, some Q estimates appeared lower than GWU, however, this does not affect our results, not our interpretation of the data.

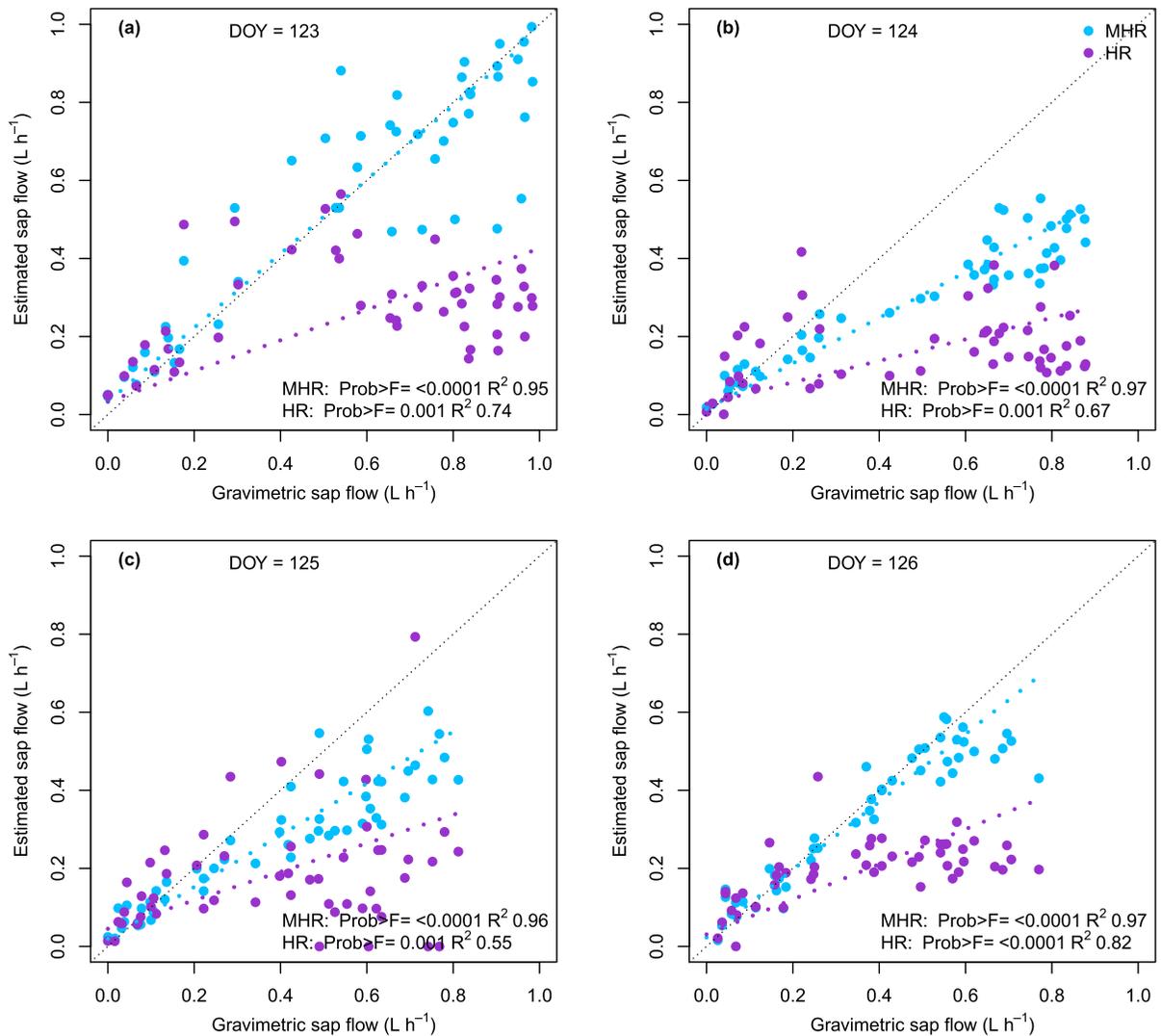


Fig. 6 Average whole-tree transpiration (Q L h⁻¹) estimated with maximum heat ratio (MHR, blue dots) and heat ratio (HR, purple) methods, compared with mean gravimetric water use.

Mean gravimetric water use was estimated using all monitored trees. Dotted lines represent the best linear fit between MHR and HR. Data used in this graph corresponds to tree 2

Freeze/thaw experiment

For the *A. saccharum* trunks that we subjected to freeze/thaw cycles, we observed a total F_d range from -30 to 50 (cm³ cm⁻² h⁻¹). Under these conditions, MHR and HR had nearly identical F_d estimates during freezing ($R^2=0.97$, Fig. 7), however, during thawing HR showed lower F_d , compared with MHR (up to 10 cm³ cm⁻² h⁻¹). Both MHR and HR were quite stable during both freezing and thawing, but most noise and occasional outliers were observed

during thawing when the stem temperature increased rapidly (Fig. 7). Most flows occurred during thawing (-1.2°C to -0.2°C), and while positive flows occurred mainly during thawing, the flow direction varied among sapwood depths of the same trunk, with overall positive (towards the canopy) in shallower depths, and negative flows (towards the roots) in deeper sapwood depths. When the trunks were left for more than 24 outside the freezer at room temperature (26°C), all sap flow ceased and both MHR and HR registered F_d insignificantly different from zero. A similar pattern

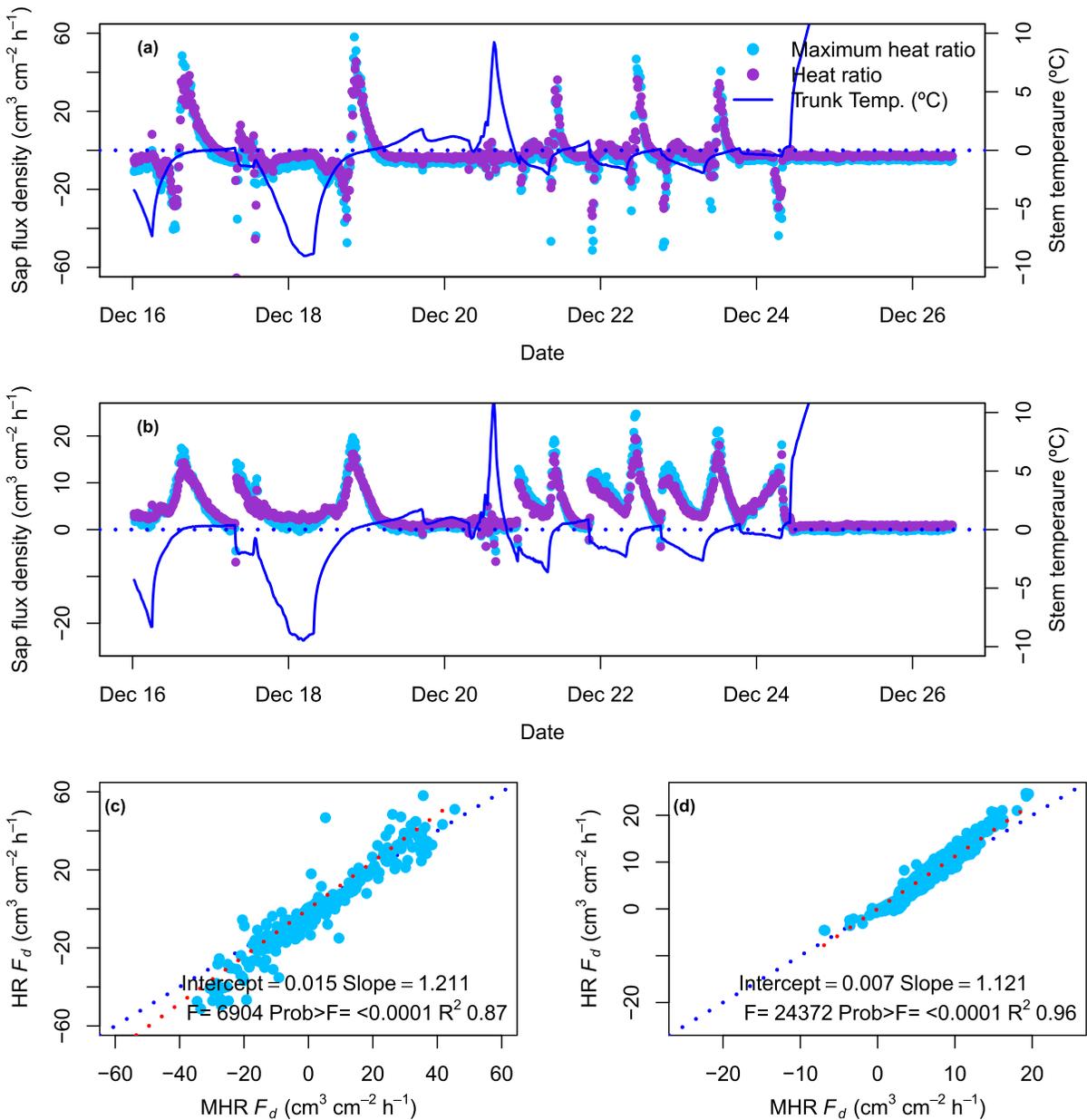


Fig. 7 Mean sap flux density (F_d , cm³ cm⁻² h⁻¹) estimated at three sapwood depths: 0.5, 1.6 and 3 cm in two *A. saccharum* trunks with the maximum heat ratio (MHR) and the heat ratio (HR) methods (**a**=stem 1; **b**=stem 2), and **c**, **d**: linear relationship between MHR and HR methods for stems 1 and

2, respectively. In all cases, we show the mean for all three sapwood depths monitored. Trunk temperature (shown in blue solid lines) is averaged across all monitored sapwood depths (0.5, 1.6, and 3 cm). Dotted line represented the best linear fit between MHR and HR

was observed when the trunks were left continuously at low (-10°C) temperatures inside the freezer. At low F_d , thermal diffusivity (D , cm² s⁻¹) and volumetric heat capacity (ρc , MJ m⁻³ K⁻¹) remained relatively

constant with changes in temperature in the cut-tree experiment, however, for the freeze/thaw experiment D and consequently ρc , showed a phase shift when temperature was below 0°C (Fig. 8). D used in Eq. 10

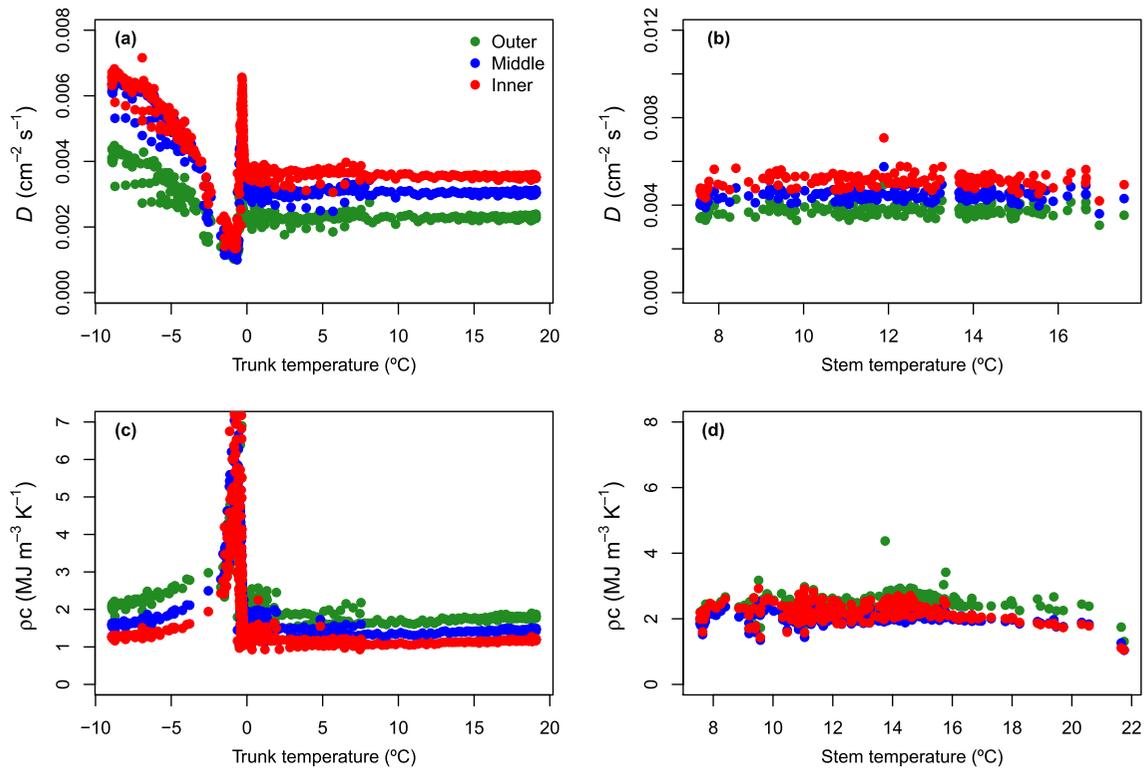


Fig. 8 Relationship between temperature and thermal diffusivity (D , $m^2 s^{-1}$), and volumetric heat capacity (ρc , $MJ m^{-3} K^{-1}$), estimated at three different depths inside the sapwood. (a) and (c) trunk 1 from our freeze/thaw experiment, (b) and (d) cor-

respond to tree 1 from the tree-cut experiment. All data was filtered to show values corresponding to sap flux density lower than $5 cm^3 cm^{-2} h^{-1}$

was kept constant, but the ρc used in Eq. 15 was estimated at 15-min intervals, which was later used to estimate F_d in Eq. 13 and increased F_d estimates.

Discussion

Measurable range of F_d , and expansion using alternative algorithms

Using the same wood properties (e.g., moisture content, density, etc.) and the same heat pulse velocity, F_d estimated with Eq. 13 is similar to sap velocity (V_s , $cm h^{-1}$) estimated following Burgess et al. (2001). Thus, we consider it appropriate to compare our results with other studies that have focused on V_s as a unit of flow. In our cut-tree experiment, on average Q estimated with the HR method was strongly correlated to GWU when F_d was within a range of $0-45 cm^3 cm^{-2} h^{-1}$, and in some trees within higher ranges (up to $0-60$ on Tree 2). The

MHR algorithm allowed for a wider range of F_d . On the first day of our experiment, we estimated F_d up to $140 cm^3 cm^{-2} h^{-1}$, and up to 120 on DOY 126, which is considerably higher than the measured range achievable with HR. A F_d range of $0-130 cm^3 cm^{-2} h^{-1}$ is higher than the maximum V_s observed in other studies and tree species: $83 cm h^{-1}$ in *E. regnans* (Vertessy et al. 1997), $33 cm h^{-1}$ in *P. patula* (Alvarado-Barrientos et al. 2013), $\sim 75 cm h^{-1}$ in *L. tulipifera* (Wullschlegler and King 2000)], and even the maximum V_s reported for *E. grandis*: $60 cm h^{-1}$ in 4-year old plantations (Benyon 1999), and $60 cm h^{-1}$ in ~ 26 year-old plantations (Kallarackal 2010). On grapevines, where the LAI to sapwood area ratios are extremely high, studies have measured maximum V_s ($cm h^{-1}$) of 110 using the Tmax method (Intrigliolo et al. 2009), which is still within the range of F_d measured with MHR.

The main reason for the low measurement F_d range of HR, is the 60 s waiting period after the release of the heat pulse before making temperature

measurements to estimate the temperature ratio. At F_d higher than approximately $55 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$, the mean ΔT from 60 to 100 s in the lower thermocouple is close to, or already zero (see Fig. 1 and Fig. 2). Under these conditions, dividing mean ΔT from 60 to 100 s between the upper and lower probes, results in a fictitious high or low temperature ratio and equivalent F_d . The 60–100 s was initially selected because of the linearity of the temperature ratio, and while they become linear as early as 40 s after the pulse, this only seems to occur under slow flows (e.g., $F_d < 55 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$) (see Fig. 2-c&g). Selecting the ΔT_{max} after the pulse in both upper and lower probes, to estimate the temperature ratio ($\Delta T_{\text{max}_u}/\Delta T_{\text{max}_d}$) avoids the fictitious F_d . In the absence of sap flow, upper- and lower-probe ΔT_{max} after the pulse are nearly identical, and temperature ratio estimated from them results in zero F_d . As F_d increases, ΔT_{max_u} increases, the ΔT_{max_d} decreases, but the later never reaches zero (see Fig. 1-d and Fig. 2-c&g). Other $\Delta T_u/\Delta T_d$ ratios should also work, but the only one that seems to remain stable over a large range of F_d ranges is the $\Delta T_{\text{max}_u}/\Delta T_{\text{max}_d}$. The differential $T_u - T_d$, which has also been proposed as an alternative to estimate V_h , seems to capture well fast flows, but it is difficult to estimate slow flows with it (see Fig. 1-c). Previously Vandegehuchte et al. (2015) showed that shifting the time frame for mean ΔT from 20–60 s, instead of 60–100 s, increase the measurement range of HR; however, when we applied this time frame to our data, F_d estimates were excessively high, and Q estimated from them did not match our gravimetric measurements. This led us to believe that shifting the time frame is valid, as long as the flows remain slow (i.e., under $20 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$). An additional advantage of the $\Delta T_{\text{max}_u}/\Delta T_{\text{max}_d}$ ratio, is that within a single ΔT (above or below the heater) curve ΔT_{max} is directly proportional to D (see Eq. 5), and since F_d is constant from the lower to the upper probe, the timing at which these two ΔT_{max_u} and ΔT_{max_d} occur is very similar, particularly within slow and medium flows (as shown in Fig. 2-a,b,e,f), making it a robust ratio that deals well with convection at slow flows, and conduction at fast flows. We also tested temperature ratios where ΔT_{max_d} was picked at the time when ΔT_{max_u} occur, and the only difference observed were higher ratios, and F_d during the peak of the flows. This was caused because at very fast flows, there is a greater transport of convective heat forcing ΔT_{max_u} to occur at an

earlier time than T_{max_d} . However, fast F_d estimates from this approach did not match GWU estimates.

The ability to measure fast F_d is of great importance in ecological and physiological research. Studies often require comparing the same species at different developmental stages, which can result in significantly different ranges of F_d . For example, Forrester et al (2010) observed fast F_d in two-year-old *Eucalyptus globulus* trees compared to eight-year-old trees (average of 13 to 6 cm h^{-1}). According to their results these changes in F_d were strongly associated with changes with age and the ratio between LAI and sapwood area (LAI/A_s). Other studies using various sap flow sensors have reported similar patterns of fast F_d when the LAI/ A_s ratios are high (Alsheimer et al. 1998; Delzon and Loustau 2005; Dye et al. 1996; Forrester et al. 2010; Kostner et al. 2002). Nonetheless, studies reporting fast F_d ($> 100 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$) on whole rooted trees are rare, likely in part due to the difficulty in conducting these measurements. Conversely, in artificial setups commonly used in sensor validation experiments, fast F_d estimates are commonly observed. For example, Vandegehuchte and Steppe (2012b) using the Sapflow+ method, estimated V_s close 150 cm h^{-1} on artificial columns filled with sawdust. Similarly, in our cut-tree experiment, the F_d estimated from our sensors were significantly higher than those on rooted trees of the same characteristics. We consider that this difference is partially the result of the removal of the root systems, which reduces the resistance to water flow into the sapwood. This can additionally help explain the faster F_d values observed in our study on the first days on the experiment. Vertessy et al. (1997) observed a similar pattern, i.e., higher F_d in the first day of a cut-tree experiment, compared to consecutive days, which they also attributed to the removal of the root system. While vessel clogging or the formation of tyloses or callus tissue around the cut stems might account for some of the reduction over time, the main reduction in our cut-tree experiment was observed from the first to the second day, and some trees showed an increment in F_d towards the end of the experiment. As observed in (Fig. 4-B), F_d for did not show a significant reduction after the second day of our experiment, making clogging or formation of tyloses less likely (see Fig. 3:a,b). Additionally, the formation of tyloses is an unlikely explanation of such reduction under short periods of time, because tyloses takes weeks

or months to form (Kitin et al. 2010; McElrone et al. 2010).

Performance of MHR under rapidly changing temperatures

As sap flow research becomes more prevalent in extreme environments (Chan and Bowling 2017), especially those where the sap is exposed to freeze/thaw cycles, understanding the role of freeze/thaw-driven sap flow and non-traditional water-loss pathways such as stem water loss or water loss from leafless branches becomes highly relevant. For example, Hölttä et al. (2018) studied sap pressurization in birch (*Betula pendula* Roth.), and discussed that HD sensors, while accurate within the growing season, might overestimate sap flow during the winter because of the various factors affecting the measuring principle of the method (i.e., the differences in temperature). This has also been highlighted by Chan and Bowling (2017) where they subjected HD sensors to conditions similar to those expected in very cold climates. In their laboratory experiments, sap flow stopped when the temperature of the stem was below the freezing point, which confirmed that HD sensors can estimate very low or zero flows, despite sudden changes in temperature. However, in both studies, the ability of the HD method to estimate F_d from differences in temperature (an important characteristic of the method), becomes a strong limitation under the extreme temperature changes observed during winter, because the method requires a thermal equilibrium at night to properly estimate F_d . Additionally, the unidirectional measurement nature of this method places limitations on the study of freeze/thaw-driven sap flow, which is often bidirectional, and often in opposite directions at different depths of the sapwood simultaneously, such as shown in Fig. 7. While not the goal of this study, we have observed in both field and laboratory experiments, that the direction of flow at a given sapwood depth results from the complex interaction between: (a) the source of the nucleation point during freezing, (b) the intensity, frequency and duration of the changes in temperature, and (c) the mass of the stem and the conducting tissue. When these factors interact in specific ways, different sections of the sapwood might be frozen at different times, resulting in flow in opposite directions. In our freeze/thaw experiment using both MHR and HR algorithms to estimate F_d , we observed that sections inside the sapwood 1.5 cm apart can, under specific conditions, have flows in opposite directions.

Under such conditions, a single measurement point, which is typical of the traditional HD method, might miss some relevant patterns that can help explain redistribution of sap for cavitation repair, or redistribution of non-structural carbohydrates during the winter months (Hartmann and Trumbore 2016; Hölttä et al. 2018; Quentin et al. 2015). While most of our F_d estimates with both MHR and HR on *A. saccharum* were under the measurement range of HR, other ongoing research studies on maple syrup production which some authors of this work are involved with, have shown F_d higher than $55 \text{ cm}^3 \text{ cm}^{-2} \text{ h}^{-1}$ in living tapped trees, when trees are subjected to natural freeze/thaw cycles (Gutierrez Lopez et al. unpublished data).

Thermal diffusivity (D , $\text{cm}^2 \text{ s}^{-1}$) in both green wood and water changes with temperature (Bonales et al. 2017; Steinhagen 1977; Vandegehuchte and Steppe 2012a) and the conditions under which ice crystals form also affect its thermal conductivity (Bonales et al. 2017). However, in most sap flow studies D is often kept constant, even when the sap temperature is below the freezing point, primarily due to the low flows expected at such temperatures. The review of changes in D with temperature and θ_v provided by Steinhagen (1977), suggests that F_d measured at low temperatures might be the result of changes in D . However, according to our results, once sapwood temperature in the *A. saccharum* trunks was lower than $-5 \text{ }^\circ\text{C}$, both MHR and HR registered near zero F_d values, so changes in D below $-5 \text{ }^\circ\text{C}$ cannot have any effect on F_d measurements. According to Bonales et al. (2017) and Steinhagen (1977), D changes significantly below $-5 \text{ }^\circ\text{C}$, in both green wood and water, which is consistent with our observations. But in our case, there was a large peak before the phase change which has not been reported before (Fig. 8), coinciding with the peaks in ρ_c estimated right below $0 \text{ }^\circ\text{C}$ (Fig. 8), which resulted in θ_v well over 300%. However, if the F_d we measured as a result of freeze/thaw cycles is primarily influenced by changes in thermal properties, such influence should disappear if D and θ_v are kept constant. This was also tested, and the measured F_d during both freezing and thawing appeared, but the amount of noise immediately below $0 \text{ }^\circ\text{C}$ was significantly reduced. Recently, we observed the same pattern in pine (*Pinus sylvestris*), spruce (*Picea abies*) and birch (*Betula pendula*) trees in an ongoing study on transpiration of boreal forests in Northern Sweden: on nearly all monitored

trees, once sapwood temperature and sap was below $-5\text{ }^{\circ}\text{C}$, no F_d was measured with either MHR nor HR, even when sapwood temperature fluctuated between $-5\text{ }^{\circ}\text{C}$ and $-13\text{ }^{\circ}\text{C}$ for several days (Gutierrez Lopez et al. 2021). Nonetheless, this opens new questions regarding how to best apply the known changes in D and ρ_c with temperature to sap flow measurements in places where transpiration occurs simultaneously with freeze/thaw cycles. If D is adjusted to changes in temperature below $0\text{ }^{\circ}\text{C}$, many flows will be significantly reduced because its main influence on V_h in Eq. 10. However, solving Eq. 4 at zero flows, results in stable ρ_c until $0\text{ }^{\circ}\text{C}$, below that, there is a significant ρ_c increment during both freezing and thawing, which as previously mentioned, directly affects θ_v in Eq. 15, and subsequently F_d in Eq. 13. Freeze/thaw cycles do not only affect thermometric sap flow sensors. We have observed similar θ_v changes with temperature fluctuations in similarly-sized *Acer saccharum* trunks that we subjected to deep ($-20\text{ }^{\circ}\text{C}$ to $20\text{ }^{\circ}\text{C}$) freeze/thaw cycles where θ_v was monitored using GS-3 capacitance sensors (METER Group, Pullman, WA, USA) (Gutierrez Lopez, unpublished data). While capacitance sensors have been calibrated and successfully used before to estimate θ_v (Matheny et al. 2017), their reliability within freeze/thaw cycles remains to be tested, especially since we know that in some species, freeze/thaw cycles results in bidirectional sap flow. Finally, we have tested MHR with both Type-T thermocouples and with high-precision thermistors, and the only difference we have observed so far is the higher measurement stability of thermistors, as long as a first-level linearization circuit is implemented in the sensor design (Baker 2002). At this moment, we are not certain whether HD sensors can be reliably used to monitor F_d during winter-time or freeze/thaw cycles, considering that the heated probe is maintained at approximately $40\text{ }^{\circ}\text{C}$, which we are certain results in a bubble of liquid sap around the heating element, potentially affecting F_d measurements during critical times during the winter.

Conclusions

The alternative MHR method allowed us to significantly increase the measurement range of HR to F_d values up to $130\text{ cm}^3\text{ cm}^{-2}\text{ h}^{-1}$, which is greater than the range reported for most tree species. In general,

the F_d estimates obtained from MHR and HR were well correlated within -45 to $45\text{ cm}^3\text{ cm}^{-2}\text{ h}^{-1}$ in the species we studied, but HR had a small overestimation memory effect only when F_d was outside the measuring range of HR. The initial $\Delta T_{\max_u}/\Delta T_{\max_d}$ ratio showed also a strong relationship with actual gravimetric water use. In smaller stems with large LAI/ A_S ratio, where F_d tends to be very fast, MHR resulted in more stable estimates and less noise than HR; however, there was a high correlation between them, and when a smoothing function was applied to both, no significant differences were observed. In this study, which is based on field measurements and laboratory experiments, we show that MHR is a viable alternative that can be easily implemented in equidistant-probe HP sensor designs to monitor inverse, slow and fast flux densities. On Campbell Scientific (Campbell Scientific Inc.) data loggers, only minor variations to a CRBasic script are needed to run both MHR and HR simultaneously (so the user is not forced to pick one over the other), be processed *online* (using the data logger's memory) and stored as a single value per measurement with limited programming. Additionally, if no data memory restrictions exist, all raw data can be stored and both HR and MHR algorithms can be run for comparison purposes *a posteriori*, from where thermal properties and sapwood volumetric water content in the stem can be estimated. Because new/improved algorithms are constantly under development, we strongly advice to save raw data at no less than 1 Hz (although multiplexing speeds might make this difficult under some configurations). Finally, this algorithm can also be applied on previously collected raw data, if HR was unable to predict F_d values higher than $60\text{ cm}^3\text{ cm}^{-2}\text{ h}^{-1}$. However, as a final conclusion, further research and experiments under controlled conditions on different species and wood anatomies are needed to understand how thermal diffusivity and thermal conductivity at low temperatures affect sap flow estimates.

Authors' contributions JGL performed the experiments, analyzed the data, wrote the first manuscript draft, and build upon the initial MHR algorithm to incorporate thermal properties and volumetric water content. TP, JL, and HA conceived the overarching project, helped with international collaborations, and provided help revising manuscript drafts. SB helped revising manuscript drafts, shared the initial idea of the MHR algorithm with the team.

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Data availability Data available in the following repository: <https://github.com/joseagl/MHR>

Code availability CRBasic codes to run the MHR and HR algorithms are fully available in the following repository: <https://github.com/joseagl/MHR>

Declarations

Conflicts of interest/Competing interests Stephen Burgess receives royalties from HRM sensors marketed by ICT International Pty Ltd (not used in this study).

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